

5495A/DM7495 4-Bit Parallel Access Shift Registers

General Description

These 4-bit registers feature parallel and serial inputs, parallel outputs, mode control, and two clock inputs. The registers have three modes of operation.

Parallel (broadside) load

Shift right (the direction Q_A toward Q_D)

Shift left (the direction QD toward QA)

Parallel loading is accomplished by applying the four bits of data and taking the mode control input high. The data is loaded into the associated flip-flops and appears at the outputs after the high-to-low transition of the clock-2 input. During loading, the entry of serial data is inhibited.

Shift right is accomplished on the high-to-low transition of clock 1 when the mode control is low; shift left is accomplished on the high-to-low transition of clock 2 when the

mode control is high by connecting the output of each flipflop to the parallel input of the previous flip-flop (Q_D to input C, etc.) and serial data is entered at input D. The clock input may be applied simultaneously to clock 1 and clock 2 if both modes can be clocked from the same source.

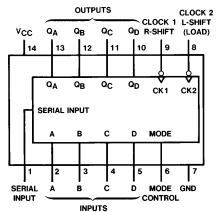
Changes at the mode control input should normally be made while both clock inputs are low; however, conditions described in the last three lines of the truth table will also ensure that register contents are protected.

Features

- Typical maximum clock frequency 36 MHz
- Typical power dissipation 250 mW

Connection Diagram

Dual-In-Line Package



TL/F/6534-1

Order Number 5495ADMQB, 5495AFMQB or DM7495N See NS Package Number J14A, N14A or W14B

Absolute Maximum Ratings (Note)

If Military/Aerospace specified devices are required, please contact the National Semiconductor Sales Office/Distributors for availability and specifications.

Supply Voltage 7V
Input Voltage 5.5V
Operating Free Air Temperature Range

Storage Temperature Range -65°C to $+150^{\circ}\text{C}$

Note: The "Absolute Maximum Ratings" are those values beyond which the safety of the device cannot be guaranteed. The device should not be operated at these limits. The parametric values defined in the "Electrical Characteristics" table are not guaranteed at the absolute maximum ratings. The "Recommended Operating Conditions" table will define the conditions for actual device operation.

Recommended Operating Conditions

| Symbol | Parameter | | | 5495A | | | Units | | |
|------------------|---|---------|-----|-------|------|-----|-------|-------|-----|
| Зушьог | Paramet | Min | Nom | Max | Min | Nom | Max | Uiits | |
| V _{CC} | Supply Voltage | 4.5 | 5 | 5.5 | 4.75 | 5 | 5.25 | V | |
| V _{IH} | High Level Input V | oltage | 2 | | | 2 | | | V |
| V_{IL} | Low Level Input Vo | oltage | | | 0.8 | | | 0.8 | V |
| Гон | High Level Output Current | | | | -0.8 | | | -0.8 | mA |
| loL | Low Level Output Current | | | | 16 | | | 16 | mA |
| f _{CLK} | Clock Frequency (Note 4) | | 0 | | 25 | 0 | | 25 | MHz |
| t _W | Clock Pulse Width (Note 4) | | 15 | 11 | | 15 | | | ns |
| t _{SU} | Data Setup Time (Note 4) | | 20 | 10 | | 20 | 10 | | ns |
| t _{EN} | Time to Enable Clock (Note 4) | Clock 1 | 20 | | | 20 | | | ns |
| | | Clock 2 | 15 | | | 15 | | | |
| t _H | Data Hold Time (Note 4) | | 0 | -10 | | 0 | -10 | | ns |
| t _{IN} | Time to Inhibit Clock 1 or Clock 2 (Note 4) | | 10 | | | 10 | | | ns |
| T _A | Free Air Operating Temperature | -55 | | 125 | 0 | | 70 | °C | |

Electrical Characteristics over recommended operating free air temperature range (unless otherwise noted)

| Symbol | Parameter | Conditions | | Min | Typ (Note 1) | Max | Units | |
|-----------------|--------------------------------------|---|--------|-----|-----------------|------|-------|--|
| V_{I} | Input Clamp Voltage | $V_{CC} = Min, I_I = -12 \text{ mA}$ | | | | -1.5 | V | |
| V_{OH} | High Level Output Voltage | $V_{CC} = Min, I_{OH} = Max$ $V_{IL} = Max, V_{IH} = Min$ | | 2.4 | 3.4 | | V | |
| V_{OL} | Low Level Output Voltage | $V_{CC} = Min, I_{OL} = Max$ $V_{IH} = Min, V_{IL} = Max$ | | | 0.2 | 0.4 | ٧ | |
| I _I | Input Current @ Max Input Voltage | $V_{CC} = Max, V_I = 5.5V$ | | | | 1 | mA | |
| I _{IH} | High Level Input | V _{CC} = Max | Mode | | | 80 | μΑ | |
| | Current | $V_{\parallel} = 2.4V$ | Others | | | 40 | | |
| I _{IL} | Low Level Input | V _{CC} = Max | Mode | | | -3.2 | - mA | |
| | Current | $V_I = 0.4V$ | Others | | | -1.6 | | |
| los | Short Circuit | V _{CC} = Max | DM54 | -18 | | -57 | - mA | |
| | Output Current | (Note 2) | DM74 | -18 | | -57 | IIIA | |
| Icc | Supply Current | V _{CC} = Max (Note 3) | | | 50 | 75 | mA | |

Note 1: All typicals are at $V_{CC}=5V$, $T_A=25^{\circ}C$.

Note 2: Not more than one output should be shorted at a time.

Note 3: I_{CC} is measured with all outputs and serial input open; A, B, C, and D inputs grounded: Mode Control at 4.5V: and a momentary 3V, then ground, applied to both clock inputs.

Note 4: $T_A = 25^{\circ}C$ and $V_{CC} = 5V$.

$\textbf{Switching Characteristics} \ \ \text{at V}_{CC} = 5 \text{V and T}_{A} = 25 ^{\circ}\text{C (See Section 1 for Test Waveforms and Output Load)}$

| Symbol | Parameter | From (Input) | $R_L = 400\Omega$ | Units | |
|------------------|--|--------------------|-------------------|-------|-------|
| Cymbol | rarameter | To (Output) | Min | Max | Ointo |
| f _{MAX} | Maximum Clock Frequency | | 25 | | MHz |
| t _{PHL} | Propagation Delay Time High to Low Level Output | Clock to Output | | 35 | ns |
| t _{PLH} | Propagation Delay Time Low to High Level Output | Clock to Output | | 35 | ns |

Function Table

| Inputs | | | | | | | | Outputs | | | |
|-----------------|--------|--------------|--------|-----------------|----------------|----------------|---|-----------------|-----------------|-----------------|-----------------|
| Mode Control | Clocks | | Serial | Parallel | | | | QA | Q _B | Qc | 0- |
| | 2(L) | 1(R) | Jellal | Α | В | С | D | ФA | αB | αC | Q_D |
| Н | Н | Х | Х | Х | Х | Х | Х | Q _{A0} | Q _{B0} | Q _{C0} | Q _{D0} |
| Н | ↓ | Χ | X | a | b | С | d | a | b | C | d |
| Н | ↓ | Χ | X | Q _{B†} | $Q_{C\dagger}$ | $Q_{D\dagger}$ | d | Q _{Bn} | Q_{Cn} | Q_{Dn} | d |
| L | L | Н | X | Х | Χ | Χ | X | Q _{A0} | Q_{B0} | Q_{C0} | Q_{D0} |
| L | X | \downarrow | Н | Х | Χ | Χ | X | Н | Q_{An} | Q_{Bn} | Q_{Cn} |
| L | X | \downarrow | L | Х | Χ | Χ | X | L | Q_{An} | Q_{Bn} | Q_{Cn} |
| 1 | L | L | X | Х | Χ | Χ | X | Q _{A0} | Q_{B0} | Q_{C0} | Q_{D0} |
| \downarrow | L | L | X | Х | Χ | Χ | X | Q _{A0} | Q_{B0} | Q_{C0} | Q_{D0} |
| \downarrow | L | Н | X | Х | Χ | Χ | X | Q _{A0} | Q_{B0} | Q_{C0} | Q_{D0} |
| 1 | Н | L | X | Х | Χ | Χ | X | Q _{A0} | Q_{B0} | Q_{C0} | Q_{D0} |
| 1 | Н | Н | X | Х | Χ | Χ | Χ | Q _{A0} | Q_{B0} | Q_{C0} | Q_{D0} |

 \dagger Shifting left requires external connection of Q_B to A, Q_C to B, Q_D to C. Serial data is entered at input D.

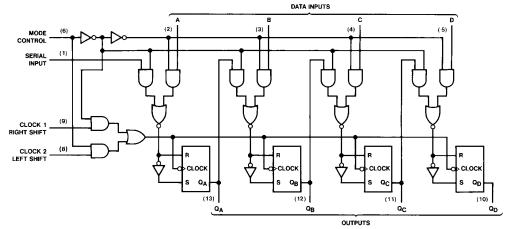
H = High Level (Steady State), L = Low Level (Steady State), X = Don't Care (Any input, including transitions)

 \downarrow = Transition from high to low level, \uparrow = Transition from low to high level

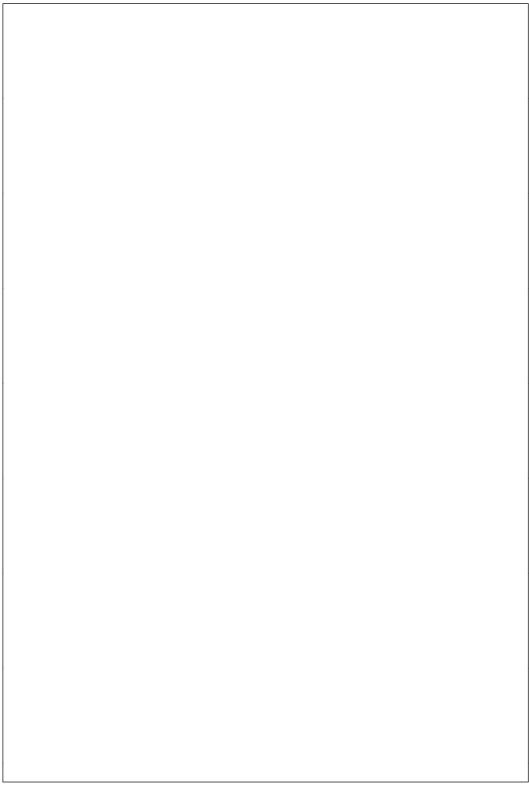
a, b, c, d = The level of steady, state input at inputs A, B, C, or D, respectively.

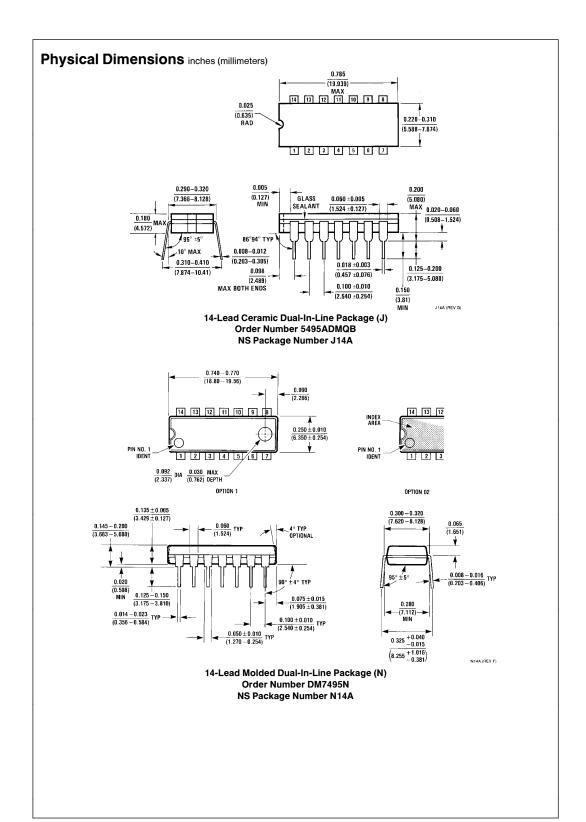
 $Q_{A0}, Q_{B0}, Q_{C0}, Q_{D0} = \text{The level of } Q_A, Q_B, Q_C, Q_D, \text{ respectively, before the indicated steady state input conditions were established.} \\ Q_{An}, Q_{Bn}, Q_{Cn}, Q_{Dn} = \text{The level of } Q_A, Q_B, Q_C, Q_D, \text{ respectively, before the most recent } \downarrow \text{ transition of the clock.} \\$

Logic Diagram

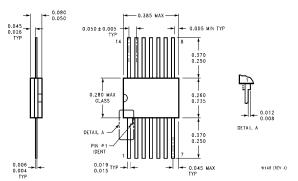


TL/F/6534-2





Physical Dimensions inches (millimeters)



14-Lead Ceramic Flat Package (W) Order Number 5495AFMQB NS Package Number W14B

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