## 54F/74F968

## 1 Mbit Dynamic RAM Controller

## General Description

The 'F968 is a high performance memory controller, replacing many SSI and MSI devices by grouping several unique functions. It provides two 10-bit address latches and two 10bit counters for row and column address generation during refresh. A 2-bit bank select latch for row and column address generation during refresh and a 2-bit bank select latch for the two high order address bits are provided to select one of the four RAS and CAS outputs.

## Features

- Provides control for $16 k, 64 k, 256 k$ or 1 Mbit DRAM systems
- Outputs directly drive up to 88 DRAMs
- Chip select for easy expansion
- Provides memory refresh with error correction mode
- 52-pin plastic leaded chip carrier


## Logic Symbol



Pin Assignment for PCC

(34) 35 36 3738 39 40 41 42 43 $44 \boxed{45}$ 46
$\mathrm{AC}_{8} \mathrm{AR}_{9} \mathrm{AC}_{9} \mathrm{SEL}_{0} \mathrm{SEL}_{1} M \mathrm{MC}_{1} \mathrm{MC}_{0} \mathrm{RASI}^{\mathrm{CAS}} \overline{S O}_{3} \overline{\mathrm{AS}}_{3} \overline{\mathrm{CAS}}_{2} \overline{\mathrm{RAS}}_{2} \mathrm{a}_{9}$

## Unit Loading/Fan Out

| Pin Names | Description | 54F/74F |  |
| :---: | :---: | :---: | :---: |
|  |  | U.L. HIGH/LOW | Input $I_{H} / I_{I L}$ Output $\mathrm{IOH}_{\mathrm{OH}} / \mathrm{l}_{\mathrm{OL}}$ |
| $\mathrm{AC}_{0}-\mathrm{AC}_{9}$ | Column Address Inputs | 1.0/1.0 | $20 \mu \mathrm{~A} /-0.6 \mathrm{~mA}$ |
| $\mathrm{AR}_{0}-\mathrm{AR}_{9}$ | Row Address Inputs | 1.0/1.0 | $20 \mu \mathrm{~A} /-0.6 \mathrm{~mA}$ |
| MC ${ }_{0}, M C_{1}$ | Mode Control Inputs | 1.0/1.0 | $20 \mu \mathrm{~A} /-0.6 \mathrm{~mA}$ |
| $\overline{\mathrm{CS}}$ | Chip Select Input | 1.0/1.0 | $20 \mu \mathrm{~A} /-0.6 \mathrm{~mA}$ |
| MSEL | Multiplexer Select Input | 1.0/1.0 | $20 \mu \mathrm{~A} /-0.6 \mathrm{~mA}$ |
| LE | Latch Enable Input | 1.0/1.0 | $20 \mu \mathrm{~A} /-0.6 \mathrm{~mA}$ |
| SELO, SEL $_{1}$ | Bank Select Inputs | 1.0/1.0 | $20 \mu \mathrm{~A} /-0.6 \mathrm{~mA}$ |
| RASI | Row Address Strobe In | 1.0/1.0 | $20 \mu \mathrm{~A} /-0.6 \mathrm{~mA}$ |
| CASI | Column Address Strobe In | 1.0/1.0 | $20 \mu \mathrm{~A} /-0.6 \mathrm{~mA}$ |
| OE | Output Enable | 1.0/1.0 | $20 \mu \mathrm{~A} /-0.6 \mathrm{~mA}$ |
| $\mathrm{RAS}_{0}-\overline{\mathrm{RAS}}_{3}$ | Row Address Strobe Outputs | 150/1.667 | $-3 \mathrm{~mA} / 1.0 \mathrm{~mA}$ |
| $\overline{\mathrm{CAS}}_{0}-\overline{\mathrm{CAS}}_{3}$ | Column Address Strobe Outputs | 150/1.667 | $-3 \mathrm{~mA} / 1.0 \mathrm{~mA}$ |
| $\mathrm{Q}_{0}-\mathrm{Q}_{9}$ | Address Outputs | 150/1.667 | -3 mA/1.0 mA |

## Pin Description

| Name | 1/0 | Description |
| :---: | :---: | :---: |
| $\begin{aligned} & \mathrm{AR}_{0}-A R_{9} \\ & A C_{0}-A C_{9} \end{aligned}$ | 1 | Address Inputs. $\mathrm{AR}_{0}-\mathrm{AR}_{9}$ are latched in as the 10-bit Row Address for the RAM. These inputs drive $Q_{0}-Q_{9}$ when the 'F968 is in the Read/Write mode and MSEL is LOW. $A C_{0}-A C_{9}$ are latched in as the Column Address, and will drive $Q_{0}-Q_{g}$ when MSEL is HIGH and the 'F968 is in the Read/Write mode. The addresses are latched with the Latch Enable (LE) signal. |
| $\mathrm{SEL}_{0}-\mathrm{SEL}_{1}$ | 1 | Bank Select. These two inputs are normally the two higher order address bits, and are used in the Read/Write mode to select which bank of memory will be receiving the $\overline{\mathrm{RAS}}_{n}$ and $\overline{\mathrm{CAS}}_{n}$ signals after RASI and CASI go HIGH. |
| LE | 1 | Latch Enable. This active-HIGH input causes the Row, Column and Bank Select latches to become transparent, allowing the latches to accept new input data. A LOW input on LE latches the input data, assuming it meets the setup and hold time requirements. |
| MSEL | 1 | Multiplexer Select. This input determines whether the Row or Column Address will be sent to the memory address inputs. When MSEL is HIGH the Column Address is selected, while the Row Address is selected when MSEL is LOW. The address may come from either the address latch or refresh address counter depending on $\mathrm{MC}_{0}, \mathrm{MC}_{1}$. |
| $\overline{\overline{C S}}$ | 1 | Chip Select. This active-LOW input is used to enable the 'F968. When $\overline{\mathrm{CS}}$ is active, the 'F968 operates normally in all four modes. When $\overline{\mathrm{CS}}$ goes HIGH, the device will not enter the Read/Write mode. This allows other devices to access the same memory that the 'F968 is controlling (e.g., DMA controller;. |
| $\overline{O E}$ | 1 | Output Enable. This active-LOW input enables/disables the output signals. When $\overline{\mathrm{OE}}$ is HIGH, the outputs of the 'F968 enter the high impedance state. The $\overline{\mathrm{OE}}$ signal allows more than one 'F968 to control the same memory, thus providing an easy method to expand the memory size. |
| $\mathrm{MC}_{0}, \mathrm{MC}_{1}$ | 1 | Mode Control. These inputs are used to specify which of the four operating modes the 'F968 should be using. The description of the four operating modes is given in the Mode Control Function Table. |
| $\mathrm{Q}_{0}-\mathrm{Q}_{9}$ | 0 | Address Outputs. These address outputs will feed the DRAM address inputs and provide drive for memory systems up to 500 pF in capacitance. |
| RASI | 1 | Row Address Strobe Input. During normal memory cycles, the decoded $\overline{\mathrm{RAS}}_{n}$ output ( $\overline{\mathrm{RAS}}_{0}, \overline{\mathrm{RAS}}_{1}$, $\overline{\mathrm{RAS}}_{2}$ or $\overline{\mathrm{RAS}}_{3}$ ) is forced LOW after receipt of RASI. In either refresh mode, all four $\overline{\mathrm{RAS}}_{n}$ outputs will go LOW following RASI going HIGH. |
| $\overline{\mathrm{RAS}}_{0}-\overline{\mathrm{RAS}}_{3}$ | 0 | Row Address Strobe. Each one of the Row Address Strobe outputs provides a $\overline{\mathrm{RAS}}_{\mathrm{n}}$ signal to one of the four banks of dynamic memory. Each will go LOW only when selected by SEL $L_{0}$ and $\mathrm{SEL}_{1}$ and only after RASI goes HIGH. All four go LOW in response to RASI in either of the Refresh modes. |
| CASI | 1 | Column Address Strobe Input. This input going active will cause the selected $\overline{\mathrm{CAS}}_{n}$ output to be forced LOW. |
| $\overline{\mathrm{CAS}}_{0}-\overline{\mathrm{CAS}}_{3}$ | 0 | Column Address Strobe. During normal Read/Write cycles the two select bits (SEL $\mathrm{L}_{0}$, SEL $_{1}$ ) determine which $\overline{\mathrm{CAS}}_{\mathrm{n}}$ output will go active following CASI going HIGH. When memory error correction is performed, only the $\overline{\mathrm{CAS}}_{n}$ signal selected by CNTR ${ }_{0}$ and CNTR $_{1}$ will be active. For non-error correction cycles, all four $\overline{\text { CAS }}_{n}$ outputs remain HIGH. |

## Functional Description

The 74F968 is a 1 Mbit DRAM controller which is functionally equivalent to AMD's Am29368. The 74F968 provides row/column address multiplexing, refresh address generation and bank selection for up to four banks of RAMs.
Twenty-two (22) address bits $\left(A R_{0}-A R_{9}, A C_{0}-A C_{9}\right.$ and bank select addresses $\mathrm{SEL}_{0}$ and $\mathrm{SEL}_{1}$ ) are presented to the controller. These addresses are latched by a 22-bit latch. A 22-bit counter generates the refresh address.

A 10-bit multiplexer selects the output address between the input row address, column address, refresh counter row address, column address, or zero (clear). Four RAS and four CAS outputs select the appropriate bank of RAMs and strobe in the row and column addresses.
It should be noted that the counters are cleared $\left(\mathrm{MC}_{0}, \mathrm{MC}_{1}\right.$ $=1,1$ ) on the next RASI transition, but the Q outputs are asynchronously cleared through the multiplexer.

## Mode Control Function Table

| MC ${ }_{1}$ | $\mathrm{MC}_{0}$ | Operating Mode |
| :---: | :---: | :---: |
| L | L | Refresh without Error Correction-Refresh cycles are performed with only the Row Counter being used to generate addresses. In this mode, all four $\overline{\operatorname{RAS}}_{n}$ outputs are active while the four $\overline{\mathrm{CAS}}_{n}$ signals are kept HIGH. |
| L | H | Refresh with Error Correction/Initialize—During this mode, refresh cycles are done with both the Row and Column counters generating the addresses. MSEL is used to select between the Row and Column counter. All four $\overline{\operatorname{RAS}}_{n}$ outputs go active in response to RASI, while only one $\overline{\mathrm{CAS}}_{n}$ output goes LOW in response to CASI. The Bank Counter keeps track of which $\overline{\mathrm{CAS}}_{n}$ output will go active. This mode of operation is possible when supported by an error detection/correction circuit such as the 'F632. |
| H | L | Read/Write- This mode is used to perform Read/Write cycles. Both the Row and Column addresses are latched and multiplexed to the address output lines using MSEL; SEL ${ }_{0}$ and $S E L_{1}$ are decoded to determine which $\overline{\operatorname{RAS}}_{n}$ and $\overline{\mathrm{CAS}}_{n}$ will be active. |
| H | H | Clear Refresh Counter- This mode will clear the three refresh counters (Row, Column and Bank) on the HIGH-to-LOW transition of RASI, putting them at the start of the refresh sequence. In this mode, all four $\overline{\mathrm{RAS}}_{n}$ outputs are driven LOW upon receipt of RASI so that DRAM wake-up cycles are performed. This mode also asynchronously clears the $Q_{n}$ outputs. |

H $=$ HIGH Voltage Level
L = LOW Voltage Level
Address Output Function Table

| $\overline{\text { CS }}$ | MC ${ }_{1}$ | MC ${ }_{0}$ | MSEL | Mode | MUX Output |
| :---: | :---: | :---: | :---: | :---: | :---: |
| L | L | L | X | Refresh without Error Correction | Row Counter Address |
|  | L | H | H | Refresh with Error Correction | Column Counter Address |
|  |  |  | L |  | Row Counter Address |
|  | H | L | H | Read/Write | Column Address Latch |
|  |  |  | L |  | Row Address Latch |
|  | H | H | X | Clear Refresh Counter | Zero |
| H | L | L | X | Refresh without Error Correction | Row Counter Address |
|  | L | H | H | Refresh with Error Correction | Column Counter Address |
|  |  |  | L |  | Row Counter Address |
|  | H | L | X | Read/Write | Zero |
|  | H | H | X | Clear Refresh Counter | Zero |

[^0]| RAS Output Function Table |  |  |  |  |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| RASI | CS | MC ${ }_{1}$ | MC ${ }_{0}$ | SEL ${ }_{1}$ | 1 SEEL | Mode |  |  | $\overline{\mathbf{R A S}}_{\mathbf{0}}$ | $\overline{\mathbf{R A S}}_{1}$ | $\overline{\mathbf{R A S}}_{2}$ | $\overline{\mathbf{R A S}}_{3}$ |
| L | x | X | X | X | X | Non-Refresh |  |  | H | H | H | H |
| H | L | L | L | X | X | Refresh without Error Correction |  |  | L | L | L | L |
|  |  | L | H | X | X | Refresh with Error Correction |  |  | L | L | L | L |
|  |  | H | L | L | L | Read/Write |  |  | L | H | H | H |
|  |  |  |  | L | H |  |  |  | H | L | H | H |
|  |  |  |  | H | L |  |  |  | H | H | L | H |
|  |  |  |  | H | H |  |  |  | H | H | H | L |
|  |  | H | H | X | x | Clear Refresh Counter |  |  | L | L | L | L |
|  | H | L | L | x | x | Refresh without Error Correction |  |  | L | L | L | L |
|  |  | L | H |  |  | Refresh with Error Correction |  |  | L | L | L | L |
|  |  | H | L |  |  | Read/Write |  |  | H | H | H | H |
|  |  | H | H |  |  | Clear Refresh Counter |  |  | L | L | L | L |
| CAS Output Function Table |  |  |  |  |  |  |  |  |  |  |  |  |
| Inputs |  |  |  | Internal Counter |  |  | Inputs |  | Outputs |  |  |  |
| CASI | CS | MC ${ }_{1}$ | $\mathrm{MC}_{0}$ |  | $\mathrm{CNTR}_{1}$ | CNTR ${ }_{0}$ | SEL ${ }_{1}$ | SEL0 | $\mathrm{CAS}_{0}$ | $\overline{\mathbf{C A S}}{ }_{1}$ | $\overline{C A S}_{2}$ | $\overline{\mathrm{CAS}}_{3}$ |
| H | L | L | L |  | x | x | x | x | H | H | H | H |
|  |  | L | H |  | L | L | x | X | L | H | H | H |
|  |  |  |  |  | L | H |  |  | H | L | H | H |
|  |  |  |  |  | H | L |  |  | H | H | L | H |
|  |  |  |  |  | H | H |  |  | H | H | H | L |
|  |  | H | L | $x$ |  | X | L | L | L | H | H | H |
|  |  |  |  |  |  | L | H | H | L | H | H |
|  |  |  |  |  |  | H | L | H | H | L | H |
|  |  |  |  |  |  | H | H | H | H | H | L |
|  |  | H | H |  | x |  | x | X | X | H | H | H | H |
|  | H | L | L |  | X |  | X | X | x | H | H | H | H |
|  |  | L | H |  | L |  | L | x | x | L | H | H | H |
|  |  |  |  |  | L | H | H |  |  | L | H | H |
|  |  |  |  |  | H | L | H |  |  | H | L | H |
|  |  |  |  |  | H | H | H |  |  | H | H | L |
|  |  | H | L | x |  | x | x | x | H | H | H | H |
|  |  | H | H |  |  |  |  |  |  |  |  |  |  |
| L | x | X | X |  | x | x | x | x | H | H | H | H |
|  |  |  |  |  |  |  |  |  |  |  |  |  |

## Block Diagram



## Memory Cycle Timing <br> Memory Cycle Timing

The relationship between the＇F968 specifications and sys－ tem timing requirements is shown in Figures 1－6．T1，T2 and T3 represent the minimum timing requirements at the ＇F968 inputs to guarantee that the RAM timing requirements are met and that maximum system performance is achieved．

The minimum requirement for $\mathrm{T} 1, \mathrm{~T} 2$ and T 3 are as follows：

$$
\begin{aligned}
& \mathrm{T} 1_{1}^{\text {Min }}=\mathrm{t}_{\text {ASR }}+\mathrm{t}_{\text {skew }} \\
& \mathrm{T} 2 \text { Min }=\mathrm{t}_{\text {RAH }}+\mathrm{t}_{\text {skew }} \\
& \mathrm{T} 3 \text { Min }=\mathrm{T}_{\text {s }}+\mathrm{t}_{\text {skew }}+\mathrm{t}_{\text {ASC }} .
\end{aligned}
$$

See RAM data sheet for applicable values for $t_{\text {RAH }}, t_{\text {ASC }}$ and tasr $^{\text {．}}$

$$
\text { T1 Min }=1
$$



FIGURE 1. Dynamic Memory Controller Timing


TL/F/9604-6
Note A: Guaranteed maximum difference between fastest RASI to $\overline{\operatorname{RAS}}_{n}$ delay and the slowest $A_{n}$ to $Q_{n}$ delay on any single device.
Note B: Guaranteed maximum difference between fastest MSEL to $Q_{n}$ delay and the slowest RASI to $\overline{\operatorname{RAS}}_{n}$ delay on any single device. Note C: Guaranteed maximum difference between fastest CASI to $\overline{C A S}_{n}$ delay and the slowest MSEL to $Q_{n}$ delay on any single device.

FIGURE 2. Specifications Applicable to Memory Cycle Timing ( $\mathbf{M C}_{\boldsymbol{n}}=\mathbf{1 , 0}$ )

Memory Cycle Timing (Continued)


TL/F/9604-7
FIGURE 3. Desired System Timing

## Refresh Cycle Timing



Note B: Guaranteed maximum difference between fastest MSEL to $Q_{n}$ delay and the slowest RASI to $\overline{\operatorname{RAS}}_{n}$ delay on any single device. Note C: Guaranteed maximum difference between fastest CASI to $\overline{C A S}_{n}$ delay and the slowest MSEL to $Q_{n}$ delay on any single device. Note D: Guaranteed maximum difference between fastest RASI to $\overline{R A S}_{n}$ delay and the slowest $M C_{n}$ to $Q_{n}$ delay on any single device.

FIGURE 4. Specifications Applicable to Refresh Cycle Timing ( $\mathbf{M C}_{\mathbf{n}}=\mathbf{0 0 , 0 1}$ )

Refresh Cycle Timing (Continued)


TL/F/9604-9
FIGURE 5. Designed Timing-Refresh with Error Correction


FIGURE 6. Desired Timing-Refresh without Error Correction

| Absolute Maximum Ratings (Note 1) |  |
| :---: | :---: |
| If Military/Aerospace specified please contact the National Office/Distributors for availabilit | vices are required, miconductor Sales and specifications. |
| Storage Temperature | $-65^{\circ} \mathrm{C}$ to $+150^{\circ} \mathrm{C}$ |
| Ambient Temperature under Bias | $-55^{\circ} \mathrm{C}$ to $+125^{\circ} \mathrm{C}$ |
| Junction Temperature under Bias | $-55^{\circ} \mathrm{C}$ to $+175^{\circ} \mathrm{C}$ |
| $V_{C C}$ Pin Potential to Ground Pin | -0.5 V to +7.0 V |
| Input Voltage (Note 2) | -0.5 V to +7.0 V |
| Input Current (Note 2) | -30 mA to +5.0 mA |
| Voltage Applied to Output in HIGH State (with $\mathrm{V}_{\mathrm{CC}}=0 \mathrm{~V}$ ) |  |
| Standard Output | -0.5 V to $\mathrm{V}_{\mathrm{CC}}$ |
| 3-State Output | -0.5 V to +5.5 V |

Current Applied to Output in LOW State (Max) twice the rated $\mathrm{IOL}(\mathrm{mA})$
Note 1: Absolute maximum ratings are values beyond which the device may be damaged or have its useful life impaired. Functional operation under these conditions is not implied.

Note 2: Either voltage limit or current limit is sufficient to protect inputs.

## Recommended Operating

 ConditionsFree Air Ambient Temperature

| Military | $-55^{\circ} \mathrm{C}$ to $+125^{\circ} \mathrm{C}$ |
| :--- | ---: |
| Commercial | $0^{\circ} \mathrm{C}$ to $+70^{\circ} \mathrm{C}$ |
| Supply Voltage |  |
| Military | +4.5 V to +5.5 V |
| Commercial | +4.5 V to +5.5 V |

## DC Electrical Characteristics

| Symbol | Parameter |  | 54F/74F |  | Units | Vcc | Conditions |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  | Min | Typ Max |  |  |  |
| $\mathrm{V}_{\mathrm{IH}}$ | Input HIGH Voltage |  | 2.0 |  | V |  | Recognized as a HIGH Signal |
| $\mathrm{V}_{\text {IL }}$ | Input LOW Voltage |  |  | 0.8 | V |  | Recognized as a LOW Signal |
| $V_{C D}$ | Input Clamp Diode Voltage |  |  | -1.2 | V | Min | $\mathrm{I}_{\mathrm{N}}=-18 \mathrm{~mA}$ |
| $\mathrm{V}_{\mathrm{OH}}$ | Output HIGH Voltage | 54F 10\% VCC $54 \mathrm{~F} 10 \% \mathrm{~V}_{\mathrm{CC}}$ <br> 74F 10\% VCC <br> 74F 10\% VCC <br> 74F 5\% VCC <br> 74F 5\% VCC | $\begin{aligned} & 2.5 \\ & 2.4 \\ & 2.5 \\ & 2.4 \\ & 2.7 \\ & 2.7 \end{aligned}$ |  | V | Min | $\begin{aligned} & \mathrm{I}_{\mathrm{OH}}=-1 \mathrm{~mA} \\ & \mathrm{I}_{\mathrm{OH}}=-3 \mathrm{~mA} \\ & \mathrm{I}_{\mathrm{OH}}=-1 \mathrm{~mA} \\ & \mathrm{I}_{\mathrm{OH}}=-3 \mathrm{~mA} \\ & \mathrm{I}_{\mathrm{OH}}=-1 \mathrm{~mA} \\ & \mathrm{I}_{\mathrm{OH}}=-3 \mathrm{~mA} \end{aligned}$ |
| $\mathrm{V}_{\mathrm{OL}}$ | Output LOW <br> Voltage | 54F 10\% VCC <br> 54F 10\% VCC <br> 74F 10\% VCC <br> 74F 10\% VCC |  | $\begin{aligned} & 0.5 \\ & 0.8 \\ & 0.5 \\ & 0.8 \\ & \hline \end{aligned}$ | V | Min | $\begin{aligned} & \mathrm{l} \mathrm{OL}=1.0 \mathrm{~mA} \\ & \mathrm{IOL}=12 \mathrm{~mA} \\ & \mathrm{lOL}=1.0 \mathrm{~mA} \\ & \mathrm{IOL}=12 \mathrm{~mA} \end{aligned}$ |
| ${ }_{1 / H}$ | Input HIGH Current | $\begin{aligned} & 54 F \\ & 74 F \end{aligned}$ |  | $\begin{gathered} 20.0 \\ 5.0 \end{gathered}$ | $\mu \mathrm{A}$ | Max | $\mathrm{V}_{\mathrm{IN}}=2.7 \mathrm{~V}$ |
| $\mathrm{I}_{\mathrm{BVI}}$ | Input HIGH Current Breakdown Test | $\begin{aligned} & 54 \mathrm{~F} \\ & 74 \mathrm{~F} \end{aligned}$ |  | $\begin{aligned} & 100 \\ & 7.0 \end{aligned}$ | $\mu \mathrm{A}$ | Max | $\mathrm{V}_{\mathrm{IN}}=7.0 \mathrm{~V}$ |
| ICEX | Output HIGH <br> Leakage Current | $\begin{array}{r} 54 \mathrm{~F} \\ 74 \mathrm{~F} \\ \hline \end{array}$ |  | $\begin{gathered} 250 \\ 50 \\ \hline \end{gathered}$ | $\mu \mathrm{A}$ | Max | $V_{\text {OUT }}=V_{\text {CC }}$ |
| $V_{10}$ | Input Leakage Test | 74F | 4.75 |  | V | 0.0 | $\mathrm{I}_{\mathrm{ID}}=1.9 \mu \mathrm{~A}$ <br> All Other Pins Grounded |
| IOD | Output Leakage Circuit Current | 74F |  | 3.75 | $\mu \mathrm{A}$ | 0.0 | $\begin{aligned} & V_{\text {IOD }}=150 \mathrm{mV} \\ & \text { All Other Pins Grounded } \end{aligned}$ |
| I/L | Input LOW Current |  |  | -0.6 | mA | Max | $\mathrm{V}_{\text {IN }}=0.5 \mathrm{~V}$ |
| lozH | Output Leakage Current |  |  | 50 | $\mu \mathrm{A}$ | Max | $\mathrm{V}_{\text {OUT }}=2.7 \mathrm{~V}$ |
| lozl | Output Leakage Current |  |  | -50 | $\mu \mathrm{A}$ | Max | $\mathrm{V}_{\text {OUT }}=0.5 \mathrm{~V}$ |
| los | Output Short-Circuit Current |  | -60 | -150 | mA | Max | $\mathrm{V}_{\text {OUT }}=0 \mathrm{~V}$ |
| Izz | Buss Drainage Test |  |  | 500 | $\mu \mathrm{A}$ | 0.0V | $\mathrm{V}_{\text {OUT }}=5.25 \mathrm{~V}$ |
| ICCH | Power Supply Current |  |  | 300 | mA | Max | $\mathrm{V}_{\mathrm{O}}=\mathrm{HIGH}$ |
| ICCL | Power Supply Current |  |  | 300 | mA | Max | $V_{O}=$ LOW |
| ICCZ | Power Supply Current |  |  | 300 | mA | Max | $\mathrm{V}_{\mathrm{O}}=\mathrm{HIGH} Z$ |

## AC Electrical Characteristics

| Symbol | Parameter | 74F |  |  |  |  |  |  |  | Units |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | $\begin{gathered} T_{A}=+25^{\circ} \mathrm{C} \\ V_{C C}=+5.0 \mathrm{~V} \\ C_{L}=50 \mathrm{pF} \end{gathered}$ |  |  | $\begin{gathered} T_{A}, V_{C C}=C o m \\ C_{L}=50 \mathrm{pF} \end{gathered}$ |  | $\begin{gathered} T_{A}, V_{C C}=C o m \\ C_{L}=500 \mathrm{pF}^{*} \end{gathered}$ |  |  |  |
|  |  | Min | Typ | Max | Min | Max | Min | Typ | Max |  |
| $\begin{aligned} & t_{\text {PLH }} \\ & t_{\text {PHL }} \end{aligned}$ | Propagation Delay AR to $Q_{n}$ | $\begin{aligned} & 3.0 \\ & 3.0 \\ & \hline \end{aligned}$ | $\begin{aligned} & 7.0 \\ & 7.0 \end{aligned}$ | $\begin{aligned} & 11.0 \\ & 11.0 \\ & \hline \end{aligned}$ | $\begin{aligned} & 2.5 \\ & 2.5 \end{aligned}$ | $\begin{aligned} & 12.0 \\ & 12.0 \end{aligned}$ |  | $\begin{aligned} & 19.0 \\ & 22.0 \end{aligned}$ |  | ns |
| $t_{\text {PLH }}$ $\mathrm{t}_{\mathrm{PHL}}$ | Propagation Delay $A C$ to $Q_{n}$ | $\begin{array}{r} 3.0 \\ 3.0 \\ \hline \end{array}$ | $\begin{aligned} & 7.0 \\ & 7.0 \\ & \hline \end{aligned}$ | $\begin{aligned} & 11.0 \\ & 11.0 \\ & \hline \end{aligned}$ | $\begin{aligned} & 2.5 \\ & 2.5 \\ & \hline \end{aligned}$ | $\begin{aligned} & 12.0 \\ & 12.0 \\ & \hline \end{aligned}$ |  | $\begin{array}{r} 19.0 \\ 22.0 \\ \hline \end{array}$ |  | ns |
| $\begin{aligned} & \mathrm{t}_{\mathrm{PLH}} \\ & \mathrm{t}_{\mathrm{PHL}} \\ & \hline \end{aligned}$ | Propagation Delay RASI to $\overline{\operatorname{RAS}}_{n}$ | $\begin{aligned} & 3.5 \\ & 3.5 \\ & \hline \end{aligned}$ | $\begin{aligned} & 8.0 \\ & 7.0 \\ & \hline \end{aligned}$ | $\begin{aligned} & 12.0 \\ & 12.0 \\ & \hline \end{aligned}$ | $\begin{aligned} & 3.0 \\ & 3.0 \\ & \hline \end{aligned}$ | $\begin{aligned} & 13.0 \\ & 13.0 \\ & \hline \end{aligned}$ |  | $\begin{aligned} & 23.0 \\ & 20.0 \\ & \hline \end{aligned}$ |  | ns |
| $t_{\text {PLH }}$ $\mathrm{t}_{\mathrm{PHL}}$ | Propagation Delay CASI to $\overline{\mathrm{CAS}}_{\mathrm{n}}$ | $\begin{aligned} & 1.0 \\ & 1.0 \\ & \hline \end{aligned}$ | $\begin{aligned} & 6.0 \\ & 4.0 \\ & \hline \end{aligned}$ | $\begin{aligned} & 8.0 \\ & 8.0 \\ & \hline \end{aligned}$ | $\begin{aligned} & 1.0 \\ & 1.0 \\ & \hline \end{aligned}$ | $\begin{aligned} & 8.5 \\ & 8.5 \\ & \hline \end{aligned}$ |  | $\begin{array}{r} 19.0 \\ 17.0 \\ \hline \end{array}$ |  | ns |
| $\mathrm{t}_{\mathrm{PLH}}$ $\mathrm{t}_{\mathrm{PHL}}$ | Propagation Delay MSEL to $Q_{n}$ | $\begin{aligned} & 3.0 \\ & 3.0 \\ & \hline \end{aligned}$ | $\begin{aligned} & \hline 9.0 \\ & 8.0 \\ & \hline \end{aligned}$ | $\begin{aligned} & 13.0 \\ & 13.0 \\ & \hline \end{aligned}$ | $\begin{aligned} & 2.5 \\ & 2.5 \\ & \hline \end{aligned}$ | $\begin{aligned} & 14.0 \\ & 14.0 \\ & \hline \end{aligned}$ |  | $\begin{array}{r} 24.0 \\ 21.0 \\ \hline \end{array}$ |  | ns |
| $t_{\text {PLH }}$ $\mathrm{t}_{\mathrm{PHL}}$ | Propagation Delay $M C_{n}$ to $Q_{n}$ | $\begin{array}{r} 4.0 \\ 4.0 \\ \hline \end{array}$ | $\begin{gathered} 10.0 \\ 9.0 \\ \hline \end{gathered}$ | $\begin{array}{r} 15.0 \\ 15.0 \\ \hline \end{array}$ | $\begin{aligned} & 3.5 \\ & 3.5 \\ & \hline \end{aligned}$ | $\begin{array}{r} 16.0 \\ 16.0 \\ \hline \end{array}$ |  | $\begin{array}{r} 25.0 \\ 22.0 \\ \hline \end{array}$ |  | ns |
| $t_{\text {PLH }}$ $\mathrm{t}_{\mathrm{PHL}}$ | Propagation Delay $M C_{n}$ to $\overline{\operatorname{RAS}}_{n}$ | $\begin{array}{r} 3.5 \\ 3.5 \\ \hline \end{array}$ | $\begin{array}{r} 11.0 \\ 8.0 \\ \hline \end{array}$ | $\begin{aligned} & 17.5 \\ & 17.5 \\ & \hline \end{aligned}$ | $\begin{aligned} & 3.0 \\ & 3.0 \\ & \hline \end{aligned}$ | $\begin{array}{r} 18.5 \\ 18.5 \\ \hline \end{array}$ |  | $\begin{array}{r} 24.0 \\ 22.0 \\ \hline \end{array}$ |  | ns |
| $t_{P L H}$ $\mathrm{t}_{\mathrm{PHL}}$ | Propagation Delay $\mathrm{MC}_{n}$ to $\overline{\mathrm{CAS}}_{n}$ | $\begin{aligned} & 4.0 \\ & 4.0 \\ & \hline \end{aligned}$ | $\begin{aligned} & \hline 8.0 \\ & 9.0 \\ & \hline \end{aligned}$ | $\begin{aligned} & 12.5 \\ & 12.5 \\ & \hline \end{aligned}$ | $\begin{aligned} & 3.5 \\ & 3.5 \end{aligned}$ | $\begin{aligned} & 13.5 \\ & 13.5 \\ & \hline \end{aligned}$ |  | $\begin{array}{r} 23.0 \\ 21.0 \\ \hline \end{array}$ |  | ns |
| $\begin{aligned} & \mathrm{t}_{\mathrm{PLH}} \\ & \mathrm{t}_{\mathrm{PHL}} \\ & \hline \end{aligned}$ | Propagation Delay LE to $\overline{\operatorname{RAS}}_{\mathrm{n}}$ | $\begin{array}{r} 4.0 \\ 4.0 \\ \hline \end{array}$ | $\begin{gathered} 10.0 \\ 9.0 \\ \hline \end{gathered}$ | $\begin{array}{r} 15.0 \\ 15.0 \\ \hline \end{array}$ | $\begin{aligned} & 3.5 \\ & 3.5 \\ & \hline \end{aligned}$ | $\begin{array}{r} 16.0 \\ 16.0 \\ \hline \end{array}$ |  | $\begin{array}{r} 25.0 \\ 24.0 \\ \hline \end{array}$ |  | ns |
| $\begin{aligned} & \mathrm{t}_{\mathrm{PLH}} \\ & \mathrm{t}_{\mathrm{PHL}} \\ & \hline \end{aligned}$ | Propagation Delay LE to $\mathrm{CAS}_{\mathrm{n}}$ | $\begin{aligned} & 5.0 \\ & 5.0 \end{aligned}$ | $\begin{aligned} & 9.0 \\ & 9.0 \\ & \hline \end{aligned}$ | $\begin{aligned} & 13.5 \\ & 13.5 \\ & \hline \end{aligned}$ | $\begin{aligned} & 4.5 \\ & 4.5 \\ & \hline \end{aligned}$ | $\begin{aligned} & 14.5 \\ & 14.5 \\ & \hline \end{aligned}$ |  | $\begin{array}{r} 24.0 \\ 24.0 \\ \hline \end{array}$ |  | ns |
| $\begin{aligned} & \mathrm{t}_{\mathrm{PLH}} \\ & \mathrm{t}_{\mathrm{PHL}} \\ & \hline \end{aligned}$ | Propagation Delay LE to $Q_{n}$ | $\begin{aligned} & 3.5 \\ & 3.5 \\ & \hline \end{aligned}$ | $\begin{aligned} & 8.0 \\ & 7.0 \\ & \hline \end{aligned}$ | $\begin{array}{r} 12.0 \\ 12.0 \\ \hline \end{array}$ | $\begin{aligned} & 3.0 \\ & 3.0 \\ & \hline \end{aligned}$ | $\begin{aligned} & 13.0 \\ & 13.0 \\ & \hline \end{aligned}$ |  | $\begin{array}{r} 23.0 \\ 22.0 \\ \hline \end{array}$ |  | ns |
| $t_{\text {PLH }}$ $\mathrm{t}_{\mathrm{PHL}}$ | Propagation Delay $\bar{C} \bar{S}$ to $Q_{n}$ | $\begin{aligned} & 3.0 \\ & 3.0 \\ & \hline \end{aligned}$ |  | $\begin{array}{r} 14.5 \\ 14.5 \\ \hline \end{array}$ | $\begin{aligned} & 3.0 \\ & 3.0 \end{aligned}$ | $\begin{aligned} & 15.5 \\ & 15.5 \\ & \hline \end{aligned}$ |  | $\begin{aligned} & 25.0 \\ & 23.0 \\ & \hline \end{aligned}$ |  | ns |
| ${ }^{\text {tpLH }}$ <br> ${ }^{\text {t }}{ }^{\text {PHL }}$ | Propagation Delay $\overline{\mathrm{CS}}$ to $\overline{\mathrm{RAS}}_{\mathrm{n}}$ | $\begin{aligned} & 3.5 \\ & 3.5 \\ & \hline \end{aligned}$ |  | $\begin{aligned} & 13.0 \\ & 13.0 \\ & \hline \end{aligned}$ | $\begin{aligned} & 3.0 \\ & 3.0 \\ & \hline \end{aligned}$ | $\begin{array}{r} 14.0 \\ 14.0 \\ \hline \end{array}$ |  | $\begin{array}{r} 23.0 \\ 23.0 \\ \hline \end{array}$ |  | ns |
| tPLH $\mathrm{t}_{\mathrm{PHL}}$ | Propagation Delay $\overline{\mathrm{CS}}$ to $\overline{\mathrm{CAS}}_{\mathrm{n}}$ | $\begin{array}{r} 4.0 \\ 4.0 \\ \hline \end{array}$ | $\begin{aligned} & 8.0 \\ & 8.0 \\ & \hline \end{aligned}$ | $\begin{aligned} & 11.5 \\ & 11.5 \\ & \hline \end{aligned}$ | $\begin{aligned} & 3.5 \\ & 3.5 \\ & \hline \end{aligned}$ | $\begin{aligned} & 12.5 \\ & 12.5 \\ & \hline \end{aligned}$ |  | $\begin{aligned} & 23.0 \\ & 23.0 \\ & \hline \end{aligned}$ |  | ns |
| $\begin{aligned} & \mathrm{t}_{\mathrm{PLH}} \\ & \mathrm{t}_{\mathrm{PHL}} \\ & \hline \end{aligned}$ | Propagation Delay $S E L_{n}$ to $\overline{\operatorname{RAS}}_{n}$ | $\begin{array}{r} 4.0 \\ 4.0 \\ \hline \end{array}$ | $\begin{aligned} & 9.0 \\ & 8.0 \\ & \hline \end{aligned}$ | $\begin{array}{r} 15.5 \\ 15.5 \\ \hline \end{array}$ | $\begin{aligned} & 3.5 \\ & 3.5 \\ & \hline \end{aligned}$ | $\begin{aligned} & 16.0 \\ & 16.0 \\ & \hline \end{aligned}$ |  | $\begin{array}{r} 24.0 \\ 23.0 \\ \hline \end{array}$ |  | ns |
| $\begin{aligned} & \mathrm{t}_{\mathrm{PLH}} \\ & \mathrm{t}_{\mathrm{PHL}} \\ & \hline \end{aligned}$ | Propagation Delay $\mathrm{SEL}_{n}$ to $\overline{\mathrm{CAS}}_{\mathrm{n}}$ | $\begin{array}{r} 4.5 \\ 4.5 \\ \hline \end{array}$ | $\begin{aligned} & 9.0 \\ & 9.0 \\ & \hline \end{aligned}$ | $\begin{array}{r} 14.5 \\ 14.5 \\ \hline \end{array}$ | $\begin{aligned} & 4.0 \\ & 4.0 \\ & \hline \end{aligned}$ | $\begin{array}{r} 15.5 \\ 15.5 \\ \hline \end{array}$ |  | $\begin{aligned} & 24.0 \\ & 24.0 \\ & \hline \end{aligned}$ |  | ns |

- These values are given for typical derivative with a 500 pF load; these are not guaranteed specifications.


## AC Electrical Characteristics

| Symbol | Parameter | 74F |  |  |  |  | Units |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | $\begin{gathered} \mathrm{T}_{\mathrm{A}}=+25^{\circ} \mathrm{C} \\ \mathrm{~V}_{\mathrm{CC}}=+5.0 \mathrm{~V} \\ \mathrm{C}_{\mathrm{L}}=50 \mathrm{pF} \end{gathered}$ |  |  | $\begin{gathered} T_{A}, V_{C C}=C o m \\ C_{L}=50 p F \end{gathered}$ |  |  |
|  |  | Min | Typ | Max | Min | Max |  |
| $\begin{aligned} & \mathbf{t}_{\mathrm{PHZ}} \\ & \mathbf{t}_{\mathrm{PLLZ}} \end{aligned}$ | Output Disable Time $\overline{O E}$ to $Q_{n}$ | $\begin{aligned} & 1.0 \\ & 1.0 \end{aligned}$ | $\begin{aligned} & 5.0 \\ & 4.0 \end{aligned}$ | $\begin{aligned} & 9.5 \\ & 9.5 \end{aligned}$ | $\begin{aligned} & 1.0 \\ & 1.0 \end{aligned}$ | $\begin{aligned} & 10.0 \\ & 10.0 \end{aligned}$ | ns |
| $\begin{aligned} & \mathbf{t}_{\mathrm{P} Z \mathrm{H}} \\ & \mathrm{t}_{\mathrm{PZL}} \end{aligned}$ | Output Enable Time $\overline{O E}$ to $Q_{n}$ | $\begin{aligned} & 1.0 \\ & 1.0 \end{aligned}$ | $\begin{aligned} & 5.0 \\ & 6.0 \end{aligned}$ | $\begin{aligned} & 9.5 \\ & 9.5 \end{aligned}$ | $\begin{aligned} & 1.0 \\ & 1.0 \end{aligned}$ | $\begin{aligned} & 10.0 \\ & 10.0 \end{aligned}$ | ns |
| $\begin{aligned} & \mathrm{t}_{\mathrm{PHZ}} \\ & \mathrm{t}_{\mathrm{PLL}} \end{aligned}$ | Output Disable Time $\overline{\mathrm{OE}}$ to $\overline{\mathrm{RAS}}_{n}$ | $\begin{aligned} & 1.0 \\ & 1.0 \end{aligned}$ | $\begin{aligned} & 5.0 \\ & 4.0 \end{aligned}$ | $\begin{aligned} & 9.5 \\ & 9.5 \end{aligned}$ | $\begin{aligned} & 1.0 \\ & 1.0 \end{aligned}$ | $\begin{aligned} & 10.0 \\ & 10.0 \end{aligned}$ | ns |
| $\begin{aligned} & \mathrm{t}_{\mathrm{PZH}} \\ & \mathrm{t}_{\mathrm{PZL}} \\ & \hline \end{aligned}$ | Output Enable Time $\overline{\mathrm{OE}}$ to $\overline{\mathrm{RAS}}_{n}$ | $\begin{aligned} & 1.0 \\ & 1.0 \\ & \hline \end{aligned}$ | $\begin{array}{r} 5.0 \\ 6.0 \\ \hline \end{array}$ | $\begin{aligned} & 9.5 \\ & 9.5 \\ & \hline \end{aligned}$ | $\begin{aligned} & 1.0 \\ & 1.0 \\ & \hline \end{aligned}$ | $\begin{aligned} & 10.0 \\ & 10.0 \\ & \hline \end{aligned}$ | ns |
| $\begin{aligned} & \text { tpHZ } \\ & \text { tplZ } \\ & \hline \end{aligned}$ | Output Disable Time $\overline{O E}$ to $\overline{C A S}_{n}$ | $\begin{aligned} & 1.0 \\ & 1.0 \\ & \hline \end{aligned}$ | $\begin{array}{r} 5.0 \\ 4.0 \\ \hline \end{array}$ | $\begin{aligned} & 9.5 \\ & 9.5 \\ & \hline \end{aligned}$ | $\begin{aligned} & 1.0 \\ & 1.0 \\ & \hline \end{aligned}$ | $\begin{aligned} & 10.0 \\ & 10.0 \\ & \hline \end{aligned}$ | ns |
| $\begin{aligned} & \mathrm{t}_{\mathrm{PZH}} \\ & \mathrm{t}_{\mathrm{PZL}} \end{aligned}$ | Output Enable Time $\overline{\mathrm{OE}}$ to $\overline{\mathrm{CAS}}_{n}$ | $\begin{aligned} & 1.0 \\ & 1.0 \\ & \hline \end{aligned}$ | $\begin{aligned} & 5.0 \\ & 6.0 \\ & \hline \end{aligned}$ | $\begin{aligned} & 9.5 \\ & 9.5 \end{aligned}$ | $\begin{aligned} & 1.0 \\ & 1.0 \\ & \hline \end{aligned}$ | $\begin{aligned} & 10.0 \\ & 10.0 \\ & \hline \end{aligned}$ | ns |

## AC Operating Requirements

| Symbol | Parameter | 74F |  |  |  | Units |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | $\begin{aligned} & T_{A}=+25^{\circ} \mathrm{C} \\ & V_{C C}=+5.0 \mathrm{~V} \end{aligned}$ |  | $\mathrm{T}_{\mathbf{A}}, \mathrm{V}_{\mathbf{C c}}=\mathbf{C o m}$ |  |  |
|  |  | Min | Max | Min | Max |  |
| $\begin{aligned} & t_{s}(H) \\ & t_{s}(L) \\ & \hline \end{aligned}$ | Setup Time, HIGH or LOW $A_{n}$ to LE | $\begin{aligned} & 5.0 \\ & 5.0 \\ & \hline \end{aligned}$ |  | $\begin{aligned} & 5.0 \\ & 5.0 \\ & \hline \end{aligned}$ |  | ns |
| $\begin{aligned} & t_{h}(H) \\ & t_{h}(L) \end{aligned}$ | Hold Time, HIGH or LOW $A_{n}$ to LE | $\begin{aligned} & 5.0 \\ & 5.0 \\ & \hline \end{aligned}$ |  | $\begin{aligned} & 5.0 \\ & 5.0 \\ & \hline \end{aligned}$ |  | ns |
| $\begin{aligned} & \mathrm{t}_{\mathbf{s}}(\mathrm{H}) \\ & \mathrm{t}_{\mathbf{s}}(\mathrm{L}) \\ & \hline \end{aligned}$ | Setup Time, HIGH or LOW SEL to LE | $\begin{aligned} & 5.0 \\ & 5.0 \\ & \hline \end{aligned}$ |  | $\begin{aligned} & 5.0 \\ & 5.0 \\ & \hline \end{aligned}$ |  | ns |
| $\begin{aligned} & t_{h}(H) \\ & t_{h}(L) \end{aligned}$ | Hold Time, HIGH or LOW SEL to LE | $\begin{aligned} & 5.0 \\ & 5.0 \end{aligned}$ |  | $\begin{aligned} & 5.0 \\ & 5.0 \\ & \hline \end{aligned}$ |  | ns |
| $\begin{aligned} & t_{w}(H) \\ & t_{w}(L) \end{aligned}$ | Pulse Width, HIGH or LOW $\overline{\mathrm{CAS}}_{\mathrm{n}}, \overline{\operatorname{RAS}}_{\mathrm{n}}$ | $\begin{aligned} & 15.0 \\ & 15.0 \end{aligned}$ |  | $\begin{aligned} & 15.0 \\ & 15.0 \end{aligned}$ |  | ns |
| $\mathrm{t}_{\text {skew }}$ | $\mathrm{Q}_{\mathrm{n}}$ to $\overline{\mathrm{CAS}}_{\mathrm{n}}, \overline{\mathrm{RAS}}_{n}$ | 10.0 |  | 10.0 |  | ns |

## Ordering Information

The device number is used to form part of a simplified purchasing code where the package type and temperature range are defined as follows:



[^0]:    H $=$ HIGH Voltage Level
    L = LOW Voltage Level
    X = Immaterial

