# AN8737SB

## 3-channel driver IC for optical disk drive

## Overview

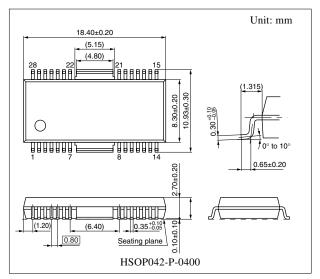
The AN8737SB is a BTL type 3-channel driver IC, adopting a current feedback system for 2 channels, which makes it optimum for an actuator and a motor driver of CD-ROM/DVD-ROM. It can also constitute an optimum system in combination with the AN8488SB, a spindle plus loading driver IC. A surface mount-type package of good heat radiation characteristic is used.

#### Features

- Little phase delay due to a current feedback system (2 channels for actuator)
- The remaining channel is available for either traverse or loading motor drive.
- Wide output dynamic range (4  $V/I_0 = 800 \text{ mA}$ )
- Standby function built in (all channels can be muted.)
- Thermal shut-down circuit built in
- With thermal flag pin

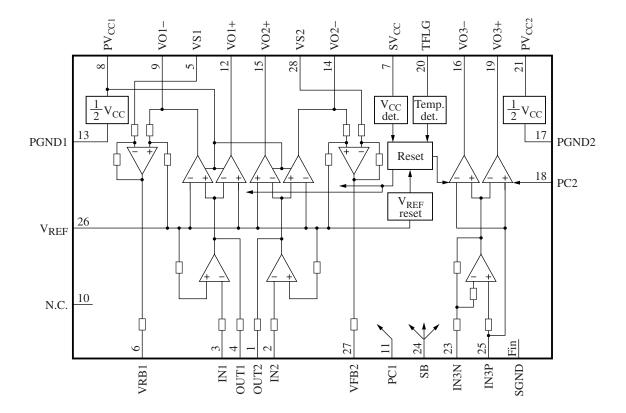
#### Applications

- CD/CD-ROM player
- DVD/DVD-ROM drive



Note) The package of this product will be changed to lead-free type (HSOP042-P-0400D). See the new package dimensions section later of this datasheet.

## Block Diagram



## Pin Descriptions

Pin No.	Description	Pin No.	Description
1	Ch. 2 first stage feedback pin	16	Ch. 3 reverse direction output pin
2	Ch. 2 first stage input pin	17	Ch. 3 power side grounding pin
3	Ch. 1 first stage input pin	18	Ch. 3 mute pin
4	Ch. 1 first stage feedback pin	19	Ch. 3 forward direction output pin
5	Ch. 1 current feedback input pin	20	TDS flag pin
6	Ch. 1 current feedback output pin	21	Ch. 3 power side power supply pin
7	Control side power supply pin	22	N.C.
8	Ch. 1 & ch. 2 power side power supply pin	23	Ch. 3 reverse rotation input pin
9	Ch. 1 reverse direction output pin	24	Standby input pin
10	N.C.	25	Ch. 3 forward rotation input pin
11	Ch. 1 & Ch. 2 mute pin	26	Reference voltage input pin
12	Ch. 2 forward direction output pin	27	Ch. 2 current feedback output pin
13	Ch. 1 & ch. 2 power side grounding pin	28	Ch. 2 current feedback input pin
14	Ch. 2 reverse direction output pin	Fin	Control side grounding pin
15	Ch. 2 forward direction output pin		

#### Absolute Maximum Ratings

Parameter	Symbol	Rating	Unit	
Supply voltage	V <sub>CC</sub>	14.0	V	
Supply voltage range	$SV_{CC}$ , $PV_{CC1}$ , $PV_{CC2}$	- 0.3 to +14.0	V	
Supply current *2	I <sub>SVCC</sub>	500	mA	
	I <sub>PVCC1</sub>	2.0	А	
	I <sub>PVCC2</sub>	800	mA	
Power dissipation *3	P <sub>D</sub>	542	mW	
Operating ambient temperature *1	T <sub>opr</sub>	-30 to +85	°C	
Storage temperature *1	T <sub>stg</sub>	-55 to +150	°C	

Note) \*1: Except for the operating ambient temperature and storage temperature, all ratings are for  $T_a = 25^{\circ}C$ .

\*2:  $I_{PVCC1}$  be 1 A or less for channel 1 and channel 2, respectively.

\*3: Use within the range of P<sub>D</sub> = 542 mW or less at T<sub>a</sub> = 85°C, following the allowable power dissipation characteristic curve of "■ Application Notes".

#### Recommended Operating Range

Parameter	Symbol	Range	Unit
Supply voltage	SV <sub>CC</sub>	4.5 to 13.5	V
	$PV_{CC1}$ , $PV_{CC2}$	3.5 to 13.5	

■ Electrical Characteristics at  $SV_{CC} = 12 \text{ V}$ ,  $PV_{CC1} = 5 \text{ V}$ ,  $PV_{CC2} = 5 \text{ V}$ ,  $R_L = 8 \Omega$ ,  $V_{REF} = 1.65 \text{ V}$ ,  $V_{SB} = V_{PC1} = V_{PC2} = 3.3 \text{ V}$ ,  $V_{IN1} = V_{IN2} = V_{IN3} = 1.65 \text{ V}$ ,  $T_a = 25^{\circ}C$ 

Parameter	Symbol	Conditions	Min	Тур	Max	Unit
Current consumption 1 (no signal)	I <sub>SVO</sub>	$V_{IN1} = V_{IN2} = V_{REF}$ , $V_{IN3P} = 2.5$ V $V_{SB} = V_{PC1} = V_{PC2} = 3.3$ V	_	25	45	mA
Current consumption 2 (no signal)	I <sub>PVO</sub>	$V_{IN1} = V_{IN2} = V_{REF}, V_{IN3P} = 2.5 V$ $V_{SB} = V_{PC1} = V_{PC2} = 3.3 V$		25	45	mA
Current consumption 1 (standby)	I <sub>SVSB</sub>	$\begin{split} V_{IN1} &= V_{IN2} = V_{REF} \ , \ V_{IN3P} = 2.5 \ V \\ V_{SB} &= V_{PC1} = V_{PC2} = 0 \ V \end{split}$		0.6	1.5	mA
Current consumption 2 (standby)	I <sub>PVSB</sub>	$V_{IN1} = V_{IN2} = V_{REF}, V_{IN3P} = 2.5 V$ $V_{SB} = V_{PC1} = V_{PC2} = 0 V$		0.2	1.0	mA
Driver 1, Driver 2 R <sub>L1</sub> , R <sub>I</sub>	$_{2} = 4 \Omega, F$	$R_{S1}$ , $R_{S2} = 0.5 \Omega$ , $R_{IN1}$ , $R_{IN2} = 10 \text{ k}\Omega$ , $R_{IN2}$	<sub>F1</sub> , R <sub>F2</sub> :	= 4.3 k <b>s</b>	2	
Output offset voltage	V <sub>OF1</sub>	$V_{IN} = V_{REF}$	-100	0	100	mV
Gain (+)	G1+	$V_{IN} = V_{REF} \pm 50 \text{ mV}$	9	11	13	dB
Relative gain (+/–)	G1		-1.5		+1.5	dB
Maximum output amplitude (+)	V <sub>L1+</sub>	$\begin{split} V_{IN} &= 3.3 \ V,  R_{L1} \ ,  R_{L2} = 4 \ \Omega \\ R_{S1} \ ,  R_{S2} &= 0.5 \ \Omega \end{split}$	3.65	4.0		V
Maximum output amplitude (–)	V <sub>L1-</sub>	$\begin{split} V_{IN} &= 0 \ V,  R_{L1} \ ,  R_{L2} = 4 \ \Omega \\ R_{S1} \ ,  R_{S2} &= 0.5 \ \Omega \end{split}$		-4.0	-3.65	V

■ Electrical Characteristics at  $SV_{CC} = 12 \text{ V}, \text{PV}_{CC1} = 5 \text{ V}, \text{PV}_{CC2} = 5 \text{ V}, \text{R}_{L} = 8 \Omega, \text{V}_{REF} = 1.65 \text{ V}, \text{V}_{SB} = \text{V}_{PC1} = \text{V}_{PC2} = 3.3 \text{ V}, \text{V}_{IN1} = \text{V}_{IN2} = \text{V}_{IN3} = 1.65 \text{ V}, \text{T}_{a} = 25^{\circ}\text{C} \text{ (continued)}$ 

Parameter	Symbol	Conditions	Min	Тур	Max	Unit		
Driver 3 $R_L = 8 \Omega$								
Output offset voltage	V <sub>OF3</sub>	$V_{IN3P} = V_{IN3N} = 2.5 V$	-150	0	150	mV		
Gain (+)	G3+	$V_{IN3P} = 2.5 V$ , $V_{IN3P} = 2.5 V \pm 50 mV$ No external resistor	19	20.5	22	dB		
Relative gain (+/–)	G3		-1.5		+1.5	dB		
Output voltage (+)	V <sub>3+</sub>	$V_{IN3N} = 5 V,$ $R_{A1} = 27 k\Omega, R_{A2} = 6.8 k\Omega$	3.05	3.4	3.75	V		
Output voltage (-)	V <sub>3-</sub>	$\begin{split} V_{IN3N} &= 0 \ V, \\ R_{A1} &= 27 \ k\Omega, \ R_{A2} &= 6.8 \ k\Omega \end{split}$	-3.75	-3.4	-3.05	V		
Input pin bias current	I <sub>IN3</sub>	$V_{IN3N} = 0 V$	_	_	1	μΑ		
Standby operation High:	Standby operation High: Active, low or Hi-Z: Standby							
High-level SB threshold voltage	V <sub>SBH</sub>	$SV_{CC} = 12 V$	2.6		—	V		
Low-level SB threshold voltage	V <sub>SBL</sub>	$SV_{CC} = 12 V$			0.7	V		
SB input current I		$V_{SB} = 5 V$		50	120	μΑ		
Power cut operation High	: Active,	low or Hiz: Power cut						
High-level PC1 threshold voltage	V <sub>PC1H</sub>	$SV_{CC} = 12 V$	2.6		—	V		
Low-level PC1 threshold voltage	V <sub>PC1L</sub>	$SV_{CC} = 12 V$			0.7	V		
High-level PC2 threshold voltage	V <sub>PC2H</sub>	$SV_{CC} = 12 V$	2.6	_	—	V		
Low-level PC2 threshold voltage	V <sub>PC2L</sub>	$SV_{CC} = 12 V$			0.7	V		
PC1 input current	I <sub>PC1</sub>	$V_{PC1} = 5 V$	—	70	120	μΑ		
PC2 input current	I <sub>PC2</sub>	$V_{PC2} = 5 V$	_	70	120	μA		
Reset current	Reset current							
Reset operation release supply voltage	V <sub>RST</sub>		_		4.5	V		
V <sub>REF</sub> detection voltage	V <sub>R</sub>		1.20			V		

#### • Design reference data

Note) The characteristics listed below are theoretical values based on the IC design and are not guaranteed.

Parameter	Symbol	Conditions	Min	Тур	Мах	Unit		
Thermal protection circuit	Thermal protection circuit							
Operating temperature equilibrium value	T <sub>THD</sub>			160		°C		
Operating temperature hysteresis width	$\Delta T_{THD}$			40		°C		
Temperature flag balancing value	T <sub>FLG</sub>			150		°C		
Temperature flag hysteresis width	$\Delta T_{FLG}$			20		°C		

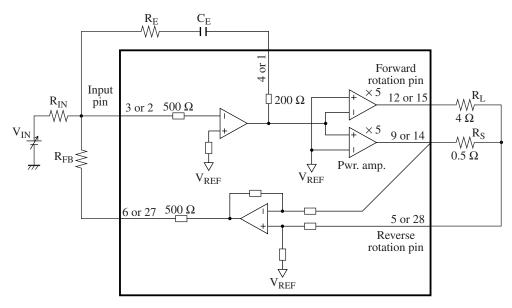
- Electrical Characteristics at  $SV_{CC} = 12 V$ ,  $PV_{CC1} = 5 V$ ,  $PV_{CC2} = 5 V$ ,  $R_L = 8 \Omega$ ,  $V_{REF} = 1.65 V$ ,
  - $V_{SB} = V_{PC1} = V_{PC2} = 3.3 \ V, \ V_{IN1} = V_{IN2} = V_{IN3} = 1.65 \ V, \ T_a = 25^{\circ}C \ (continued)$
- Design reference data (continued)

Note) The characteristics listed below are theoretical values based on the IC design and are not guaranteed.

Parameter	Symbol	Conditions	Min	Тур	Max	Unit
Thermal protection circuit (co	ntinued)					
Operating temperature difference bet. thermal protection/temperature flag	$\Delta T_{TF}$			10		°C
Temperature flag output high value	V <sub>FLH</sub>	$SV_{CC} = 12 V$		5		V
Supply voltage detection hysteresis width	$\Delta V_{HD}$			0.2		V

## Usage Notes

- 1. Use SV<sub>CC</sub> at the maximum potential. Otherwise it will cause operation error.
- 2. Do not use  $PV_{CC1}$  and  $PV_{CC2}$  at 2 V or less, or at the high impedance.
- 3. Driver 1, driver 2 gain setting (Use a resistor of sufficient power dissipation for  $R_S$  .)



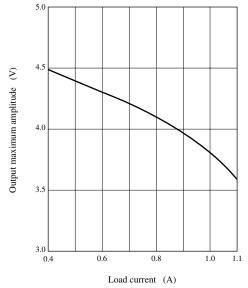
#### 4. On the mode of mute:

	SB = PC	SB = PC1 = low or Hi-Z	
	PC2 = high	PC2 = low or Hi-Z	—
Ch. 1, Ch. 2	Active	Active	All mute,
Ch. 3	Active	Mute	power save

Never fail to input the same signal into SB pin (pin 24) and PC1 pin (pin 11).

#### ■ Usage Notes (continued)

5. On the output maximum amplitude (Reference data: typical value)

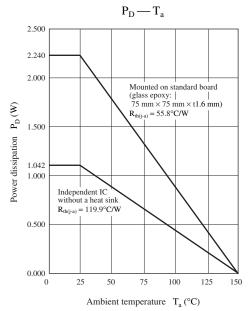


Use load current at 1 A or less.

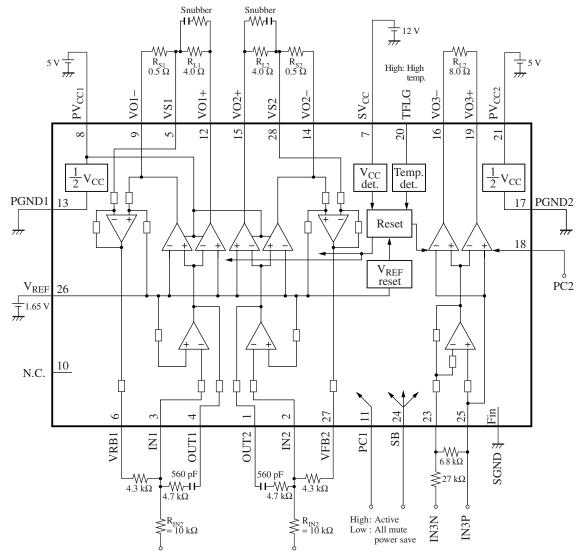
- 6 Appropriate care should be taken on the characteristics. When changing an external circuit constant on actual use, secure an appropriate margin in consideration of characteristic fluctuation of external parts and our ICs including transient characteristics as well as static ones.
- 7 Avoid the short-circuits between output pin or current detection pin and  $V_{CC}$  (line-to-supply fault), output pin or current detection pin and GND (line-to-ground fault), and output pins or output pin and current detection pin (load short-ciruit).
- 8 An appropriate prior study should be done for use of dip soldering.
- 9 Care should be taken on use of the following pin because of its low static breakdown voltage (C = 200 pF, R = 0  $\Omega$ ). Pin 18: Breakdown at 200 V

## Application Notes

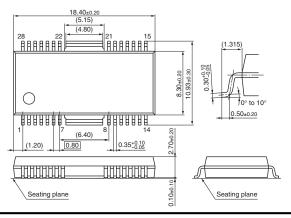
•  $P_D - T_a$  curves of HSOP042-P-0400



## Application Circuit Example



- New Package Dimensions (Unit: mm)
- HSOP042-P-0400D (Lead-free package)



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