## SAM (Supervisor And Monitor)

The ISL6550 is a precision, flexible, VID-code-controlled reference and voltage monitor for high-end microprocessor and memory power supplies. It monitors various input signals, and supervises the system (typically a DC/DC converter) with its output signals. See the Block Diagram for reference.

The ISL6550 includes a 5-bit DAC (Digital-to-Analog Converter), which is programmed by the five VID inputs. The voltage range of the BDAC (Buffered DAC output) is determined by the DACHI and DACLO voltage levels, which are externally adjustable through the R1, R2, R3 resistor divider network. VREF5 is a precision-trimmed 5 V reference, and is used to set the voltage at the top of the resistor divider.

Programmable window comparators monitor Over-Voltage (OV) and Under-Voltage (UV) levels. The OVUVSEN input, usually coming from the associated power converter device is monitored and compared with BDAC; an error band is established via the R4 and R5 resistor setting on the OVUVTH pin. An optional external capacitor on the UVDLY pin gives a programmable delay on the UV. A high gain operational amplifier is available at pins VOPP, VOPM, and VOPOUT; it can be used as a gain stage to permit monitoring voltages that are different from the BDAC levels.

The PEN (Power supply ENable) input, driven from an opencollector source, enables (when logic high) the external converter output, via the PGOOD or START outputs (both open-drain). They both basically indicate that the power supply is enabled (PEN = high) and there are no fault conditions. There are three logic options available, which determine the START and PGOOD states; see the block diagram or the Logic Options Table for more detail. The three logic options are identified with a suffix letter A, B, or C in the ordering information.

## Features

- 12 V supply operation
- 5 V reference output
- 5-bit digital-to-analog converter
- Programmable DAC Range, within $0.8-5.0 \mathrm{~V}$
- Programmable undervoltage and overvoltage thresholds, and latched fault detection
- Optional delayed undervoltage (programmable with external capacitor)
- Undervoltage lockout (power-on-reset)
- Status Indicators (START, PGOOD)
- Uncommitted operational amplifier
- Compatible with ISL6551 full bridge controller
- 20 pin SOIC and 20 lead MLFP (5x5) packages


## Applications

- Power Supplies for High End Microprocessors and Servers
- Can be paired with the ISL6551 FBC for a complete fullbridge 48V-input converter, or used independently


## Ordering Information

| PART <br> NUMBER | TEMP. RANGE <br> ( ${ }^{\circ}$ C) | PACKAGE | PKG. NO. |
| :--- | :---: | :--- | :--- |
| ISL6550AIB | -40 to 85 | 20 Lead SOIC | M20.3 |
| ISL6550BIB | -40 to 85 | 20 Lead SOIC | M20.3 |
| ISL6550CIB | -40 to 85 | 20 Lead SOIC | M20.3 |
| ISL6550AIR | -40 to 85 | 20 Lead MLFP | L20.5x5 |
| ISL6550BIR | -40 to 85 | 20 Lead MLFP | L20.5x5 |
| ISL6550CIR | -40 to 85 | 20 Lead MLFP | L20.5x5 |

NOTE: The same part numbers with a "-T" suffix are available as Tape and Reel.

## Pinouts



## Block Diagram





## Pin Descriptions

NOTE: Pin numbers refer to the 20 lead SOIC package. Please check PINOUT diagrams for MLF pin numbers.

VCC (Positive Supply Voltage) Pin 1 - This power pin supplies power to the IC; nominally 12V. It should be bypassed directly to the GND pin with a $0.1 \mu \mathrm{~F}$ low ESR/ESL capacitor.

GND (Signal Ground) Pin 6 - This power pin is the reference ground connection for the IC, and any circuitry that provides input/output to/from it.
VIDO-VID4 (DAC Digital Input Code Control) Pins 15-11 These are the DAC digital input control code lines. VIDO represents the least significant bit (LSB) and VID4 represents the most significant bit (MSB). Table 1 shows all of the codes, and their results. Note that setting all input codes low produces the maximum voltage at BDAC. The minimum voltage results when all codes are set high. Logic zero is considered system ground. A floated input or an input held higher than 2.0 V is considered a logic one level. An internal $10 \mu \mathrm{~A}$ current source pulls open VID pins to a logic high (nominal 1.6V). The pins are also TTL and LVTTL compatible.

PEN (Power Supply Enable) Pin 18 - This digital input pin enables the external converter through the START or PGOOD pins. A logic high (or float) enables the output voltage, and a logic low disables it. This pin has a $10 \mu \mathrm{~A}$ pullup current source, so it can interface with an open-collector or open-drain driver. When disabled, the START output is low and the PGOOD output is low.

OVUVTH (Over-Voltage/Under-Voltage THreshold) Pin 8 This analog input pin is used to program the window thresholds for the OV and UV comparators. The OV-UV window is centered around the BDAC voltage and can be programmed from $\pm 5 \%$ to $\pm 40 \%$ about the BDAC voltage. This pin's voltage sets the undervoltage threshold. Internal circuitry sets the overvoltage threshold such that the two thresholds are centered about BDAC, the DAC output voltage. For example, if BDAC is 2.5 V , and OVUVTH is 2.0 V ( 0.5 V below BDAC ), then the internal OV threshold is 3.0 V (0.5V above BDAC).

OVUVSEN (Over-Voltage/Under-Voltage SENse) Pin 19 This analog input pin is the sense voltage for Under-Voltage and Over-Voltage purposes. A resistor divider from the BDAC output sets the UV level, on the OVTH/UVTH pin; the IC will internally mirror a similar voltage for OV , and then compare them both to the OVUVSEN input.

DACHI (HIgh Limit of BDAC Voltage Range) Pin 9 - This analog input pin sets the high level of the BDAC, and is programmed through the external 3-resistor divider (R1, R2, R3) shown in the block diagram.

DACLO (LOw Limit of BDAC Voltage Range) Pin 10 This analog input pin sets the low level of the BDAC, and is programmed through the external 3-resistor divider shown in the block diagram.

NOTE: A total resistance of around 50 K is optimal for R1, R2, and R3. Adjust the ratios of these resistors to get the desired DACHI and DACLO voltage levels.

UVDLY (Under Voltage Delay) Pin 20 - This is an analog input/output pin. When the Under-Voltage threshold is exceeded, a potential fault is detected. A capacitor tied to the UVDLY pin is charged by an internal 10 uA source. The ramp time of the capacitor to the threshold voltage ( 5 V nominal) determines the delay. (no capacitor gives essentially no delay).

VOPP (Positive Opamp Input) Pin 2 - This analog input pin is the positive input of the Opamp.
VOPM (Minus Opamp Input) Pin 3 - This analog input pin is the minus input of the Opamp.
VOPOUT (Opamp Output) Pin 4 - This analog output pin is the output of the Opamp.

BDAC (Buffered Digital-to-Analog Converter) Pin 7 - This analog output pin is the output of the 5-bit DAC. Setting all input codes low produces the maximum voltage at BDAC. The minimum voltage results when all codes are set high. See Table 1 for codes.

VREF5 (5 Volt Reference Voltage) Pin 5 - This is an analog output pin, which provides a precision reference voltage for setting DACHI and DACLO voltage levels.
START Pin 17 - This is an open-drain pull-down digital output pin; it is pulled low when one or more of the monitored conditions is not valid; the output goes high impedance (to be pulled high externally through a pull-up resistor or equivalent) if all conditions are met. See Logic Options Table for the various conditions.

PGOOD (Power Good) Pin 18 - This is an open-drain pulldown digital output pin; it is pulled low when one or more of the monitored conditions is not valid; the output goes high impedance (to be pulled high externally through a pull-up resistor or equivalent)) if all conditions are met. See Logic Options Table for the various conditions.

## Absolute Maximum Ratings

Supply Voltage, VCC . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . +15 V Input, Output or I/O Voltage . . . . . . . . . . . . .GND -0.3V to VCC +0.3 V ESD Rating

Human Body Model (Per MIL-STD-883 Method 3015.7) . . . . .3kV
Machine Model (Per EIAJ ED-4701 Method C-111) . . . . . . . 200 V

## Operating Conditions

Supply Voltage, $\mathrm{V}_{\mathrm{CC}}$
. $+12 \mathrm{~V} \pm 10 \%$
Temperature Range . . . . . . . . . . . . . . . . . . . . . . . . . . . $-40^{\circ} \mathrm{C}$ to $85^{\circ} \mathrm{C}$ Junction Temperature Range . . . . . . . . . . . . . . . . . . $-40^{\circ} \mathrm{C}$ to $125^{\circ} \mathrm{C}$

## Thermal Information

| Thermal Resistance | $\theta_{\mathrm{JA}}\left({ }^{\circ} \mathrm{C} / \mathrm{W}\right)$ |
| :--- | :---: |
| SOIC Package (Typical, Note 1) $\ldots \ldots \ldots \ldots \ldots$ | 65 |
| MLF Package(Typical, Note 2) $\ldots \ldots \ldots \ldots \ldots$ | 33 |
| Maximum Junction Temperature (Plastic Package) | .. |
| Maximum Storage Temperature Range........... | -65 to 150 |
| Maximum Lead Temperature (Soldering 10s) $\ldots \ldots$ | 300 |
| (SOIC - Lead Tips Only) |  |

CAUTION: Stresses above those listed in "Absolute Maximum Ratings" may cause permanent damage to the device. This is a stress only rating and operation of the device at these or any other conditions above those indicated in the operational sections of this specification is not implied.

NOTE:

1. $\theta_{\mathrm{JA}}$ is measured with the component mounted on a high effective thermal conductivity test board in free air. See Tech Brief TB379 for details.
2. $\theta_{J} A$ is measured in free air with the component mounted on a high effective thermal conductivity test board with "direct attach" features. See Tech Brief TB379.

Electrical Specifications $T_{A}$ is $25^{\circ} \mathrm{C}$, and VDD $=12 \mathrm{~V}$, Unless Otherwise Specified

| PARAMETER | SYMBOL | TEST CONDITIONS | MIN | TYP | MAX | UNITS |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Supply Current |  |  |  |  |  |  |
| Input Current | $\mathrm{I}_{\mathrm{IN}}$ | $V C C=12 \mathrm{~V}$ |  | 5 | 6 | mA |
| Under-Voltage Lockout |  |  |  |  |  |  |
| $\mathrm{V}_{\text {CC }}$ UVLO Turn-on Threshold |  |  | 9.2 | 9.4 | 9.9 |  |
| $\mathrm{V}_{\text {CC }}$ UVLO Turn-off Threshold |  |  | 8.2 | 8.4 | 8.9 |  |
| VCC UVLO Threshold Hysteresis |  |  |  | 1.0 |  |  |
| DAC Reference |  |  |  |  |  |  |
| DAC Output Error (See Notes 3, 4) |  | $\begin{aligned} & \text { Step Size }=25 \mathrm{mV} \\ & \text { Vdaclo }=0.8 \mathrm{~V} \text { to } 4.225 \mathrm{~V} \\ & \text { Ibdac }=0.1 \mathrm{~mA} \text { to }-1 \mathrm{~mA} \end{aligned}$ | -2 |  | +2 | mV |
| DAC Output Error (See Notes 3, 4) |  | $\begin{aligned} & \text { Step Size }=50 \mathrm{mV} \\ & \text { Vdaclo }=0.8 \mathrm{~V} \text { to } 3.45 \mathrm{~V} \\ & \text { Ibdac }=0.1 \mathrm{~mA} \text { to }-1 \mathrm{~mA} \end{aligned}$ | -2 |  | +4 | mV |
| DAC Output Error (See Notes 3, 4) |  | $\begin{aligned} & \text { Step Size }=100 \mathrm{mV} \\ & \text { Vdaclo }=0.8 \mathrm{~V} \text { to } 1.9 \mathrm{~V} \\ & \text { Ibdac }=0.1 \mathrm{~mA} \text { to }-1 \mathrm{~mA} \end{aligned}$ | -2 |  | +6 | mV |
| VREF5 Voltage |  |  | 4.95 |  | 5.05 | V |
| VID0-VID4 Input LPUL (Vih) |  |  | 2.0 |  |  | V |
| VID0-VID4 Input MPDL (Vil) |  |  |  |  | 0.8 | V |
| VID0-VID4 Input Pull-Up Current |  | Vvidx $=0 \mathrm{~V}$ | -15 | -10 |  | $\mu \mathrm{A}$ |
| VID0-VID4 Input Leakage Current |  | Vvidx $=5 \mathrm{~V}$ |  |  | 1 | $\mu \mathrm{A}$ |
| Output Settling Time |  | $\pm 1$ LSB Error Band |  |  | 20 | $\mu \mathrm{S}$ |
| UVDLY |  |  |  |  |  |  |
| Source Current |  |  |  | -10 |  | $\mu \mathrm{A}$ |
| Sink Current |  |  |  | 10 |  | mA |
| Threshold |  |  |  | 5 |  | V |

Electrical Specifications $\quad T_{A}$ is $25^{\circ} \mathrm{C}$, and VDD $=12 \mathrm{~V}$, Unless Otherwise Specified (Continued)

| PARAMETER | SYMBOL | TEST CONDITIONS | MIN | TYP | MAX | UNITS |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Voltage Amplifier |  |  |  |  |  |  |
| Input Offset Voltage |  | All Conditions |  |  | 3.0 | mV |
| Input Bias Current |  | All Conditions |  |  | 200 | $n \mathrm{~A}$ |
| Input Offset Current |  | All Conditions |  | 20 | 50 | nA |
| Open Loop Gain |  | All Conditions | 85 |  |  | dB |
| Common-Mode Rejection Ratio |  | Vin ranges from 0 V to 6V | 80 |  |  | dB |
| Power Supply Rejection Ratio |  | 1 mA Load | 90 |  |  | dB |
| Output |  | 2 mA source or 0.2 mA sink | 0.15 |  | 5 | V |
| Maximum output current source |  | All | -2 | -7 |  | mA |
| Maximum output current sink |  | All | 0.2 | 4 |  | mA |
| Slew Rate |  | All | 4 |  |  | $v / \mu S$ |
| Phase Margin |  | 100pF load Condition |  | 45 |  | deg |
| Input Common Mode Voltage |  |  | 0 |  | 6 | V |
| Gain-Bandwidth Product |  | All | 7.4 |  |  | MHz |
| Monitor Circuitry |  |  |  |  |  |  |
| Input Common Mode Range |  | OV, UV Comparators | 0 |  | 6 | V |
| Propagation Delay |  | OV, UV Comparators |  |  | 1.0 | $\mu \mathrm{S}$ |
| PGOOD, START Outputs |  |  |  |  |  |  |
| PGOOD Voltage Low |  | $\mathrm{IPGOOD}=5.0 \mathrm{~mA}$ |  | 0.27 | 0.4 | V |
| START Voltage Low |  | ISTART $=5.0 \mathrm{~mA}$ |  | 0.21 | 0.4 | V |
| Transistor Breakdown Voltage |  | All Conditions | 15 |  |  | V |
| Transistor Leakage |  | All Conditions |  |  | 5 | $\mu \mathrm{A}$ |
| PEN |  |  |  |  |  |  |
| Input LPUL (Vih) |  |  | 2 |  |  | V |
| Input MPDL (Vil) |  |  |  |  | 0.8 | V |
| Input Pull-Up Current |  | $\mathrm{PEN}=0 \mathrm{~V}$ | -15 | -10 |  | $\mu \mathrm{A}$ |
| Input Leakage Current |  | PEN $=5 \mathrm{~V}$ |  |  | 1 | $\mu \mathrm{A}$ |
| OV/UV |  |  |  |  |  |  |
| UV and OV Threshold Hysteresis |  | \% of (Vbdac-Vovuvth); logic option B |  | 40 |  | \% |
| UV and OV Threshold Hysteresis |  | \% of (Vbdac-Vovuvth); logic options A, C |  | 10 |  | \% |

## NOTES:

3. The total resistance of R1 + R2 + R3 of $50 \mathrm{k} \Omega$ is preferred to minimize error due to DACHI and DACLO input currents. Choose the values within this limitation such that the voltages at DACHI and DACLO are those desired for the high and low limits of the programming range. For example, Choosing R1 and R2 to be 15 K and R 3 to be 20 K will produce a DAC range of 2.0 V to 3.5 V .
4. DAC Output Error as defined here assumes that the voltages applied to DACHI and DACLO are exact. The limits include errors introduced by source impedance up to 12.5 K and DACHI and DACLO. The error in Vdachi and Vdaclo (i.e. VREF5 error + external resistor divider error) must be included to arrive at the total BDAC output error.

TABLE 1. DIGITAL-TO-ANALOG (DAC) PROGRAMMING CODE

| VID4 | VID3 | VID2 | VID1 | VIDO | $\begin{gathered} \text { DACOUT } \\ \text { Vstep }=(\text { Vdachi-Vdaclo)/31 } \end{gathered}$ |
| :---: | :---: | :---: | :---: | :---: | :---: |
| 1 | 1 | 1 | 1 | 1 | Vdaclo |
| 1 | 1 | 1 | 1 | 0 | Vdaclo + 1*Vstep |
| 1 | 1 | 1 | 0 | 1 | Vdaclo + 2*Vstep |
| 1 | 1 | 1 | 0 | 0 | Vdaclo + 3*Vstep |
| 1 | 1 | 0 | 1 | 1 | Vdaclo + 4*Vstep |
| 1 | 1 | 0 | 1 | 0 | Vdaclo + * $^{\text {Vstep }}$ |
| 1 | 1 | 0 | 0 | 1 | Vdaclo $+6 *$ Vstep |
| 1 | 1 | 0 | 0 | 0 | Vdaclo + * Vstep $^{\text {a }}$ |
| 1 | 0 | 1 | 1 | 1 | Vdaclo $+8^{*}$ Vstep |
| 1 | 0 | 1 | 1 | 0 | Vdaclo + 9*Vstep |
| 1 | 0 | 1 | 0 | 1 | Vdaclo + 10*Vstep |
| 1 | 0 | 1 | 0 | 0 | Vdaclo + 11*Vstep |
| 1 | 0 | 0 | 1 | 1 | Vdaclo + 12*Vstep |
| 1 | 0 | 0 | 1 | 0 | Vdaclo $+13^{*}$ Vstep |
| 1 | 0 | 0 | 0 | 1 | Vdaclo $+14^{*}$ Vstep |
| 1 | 0 | 0 | 0 | 0 | Vdaclo + 15*Vstep |
| 0 | 1 | 1 | 1 | 1 | Vdaclo $+16^{*}$ Vstep |
| 0 | 1 | 1 | 1 | 0 | Vdaclo $+17^{*}$ Vstep |
| 0 | 1 | 1 | 0 | 1 | Vdaclo + $18^{*}$ Vstep |
| 0 | 1 | 1 | 0 | 0 | Vdaclo + 19*Vstep |
| 0 | 1 | 0 | 1 | 1 | Vdaclo $+20^{*}$ Vstep |
| 0 | 1 | 0 | 1 | 0 | Vdaclo $+21^{*}$ Vstep |
| 0 | 1 | 0 | 0 | 1 | Vdaclo + $22^{*}$ Vstep |
| 0 | 1 | 0 | 0 | 0 | Vdaclo $+23^{*}$ Vstep |
| 0 | 0 | 1 | 1 | 1 | Vdaclo + $24 *$ Vstep |
| 0 | 0 | 1 | 1 | 0 | Vdaclo + $25^{*}$ Vstep |
| 0 | 0 | 1 | 0 | 1 | Vdaclo $+26^{*}$ Vstep |
| 0 | 0 | 1 | 0 | 0 | Vdaclo $+27^{*}$ Vstep |
| 0 | 0 | 0 | 1 | 1 | Vdaclo $+28^{*}$ Vstep |
| 0 | 0 | 0 | 1 | 0 | Vdaclo + $29 *$ Vstep |
| 0 | 0 | 0 | 0 | 1 | Vdaclo $+30 *$ vstep |
| 0 | 0 | 0 | 0 | 0 | Vdaclo $+31^{*}$ Vstep $=$ Vdachi |

## Logic Options

| OPTION DEFINITIONS | A | B | C |
| :---: | :---: | :---: | :---: |
| START Pin: <br> PEN input is high AND <br> VCC is above the UVLO threshold AND | X | X | X |
| OV condition does not exist AND UVDLY condition does not exist. |  | X |  |
| Fault Latch is not set. | X |  | X |
| PGOOD Pin: <br> VCC is above the UVLO threshold AND <br> UV condition does not exist AND | X | X | X |
| OV condition does not exist AND |  | X | X |
| PEN input is high AND | X | X |  |
| Fault latch is not set. | X |  |  |
| Fault Latch Set by: <br> OV condition OR <br> UVDLY condition (UV has persisted past the UVDLY time-out) | X | (Fault Latch not used) | X |
| Fault Latch Reset by: <br> OV condition does not exist AND UVDLY condition does not exist AND VCC below UVLO threshold OR | X | (Fault Latch not used) | X |
| PEN input low |  |  | X |
| OVUV Detection: <br> UV detect threshold = Vovuvth (voltage at OVUVTH pin) <br> OV detect threshold = Vbdac + (Vbdac - Vovuvth) | X | X | X |
| UV and OV threshold hysteresis $=10 \%$ of (Vbdac - Vovuvth) | X |  | X |
| UV and OV threshold hysteresis $=40 \%$ of (Vbdac - Vovuvth) |  | X |  |

## Applications Information

Here are some step-by-step guidelines to help set up a circuit. Use the block diagram for reference.

1. Use a $12 \mathrm{~V}( \pm 10 \%)$ Power Supply; connect to VCC and GND. Connect a $0.1 \mu \mathrm{~F}$ bypass capacitor across the pins.
2. Determine the minimum and maximum DAC values required. VREF5 is a precision 5 V buffered output; connect R1, R2, R3 as a divider, to select the upper and lower range for the DAC. A total of $50 \mathrm{k} \Omega$ for the 3 resistors is recommended. The maximum for DACHI is 5.0 V ; the minimum for DACLO is 0.8 V . The difference between DACHI and DACLO, divided by 31, determines the step size of the DAC.
DACLO $=(5 \mathrm{~V}) *(R 3) /(R 1+R 2+R 3)$
$\mathrm{DACHI}=(5 \mathrm{~V}) *(\mathrm{R} 3+\mathrm{R} 2) /(\mathrm{R} 1+\mathrm{R} 2+\mathrm{R} 3)$
STEP $=(\mathrm{DACHI}-\mathrm{DACLO}) / 31$
For example, if $R 1$ is $24 \mathrm{~K}, \mathrm{R} 2$ is 16 K , and R 3 is 10 K , then DACLO $=1.0 \mathrm{~V}, \mathrm{DACHI}=2.6 \mathrm{~V}$, and STEP $=0.05 \mathrm{~V}$
3. Within the above range, select the VID code for the desired BDAC output voltage. (This is typically used as a reference for a DC/DC converter system). Connect the VID bits accordingly (GND is a logic low; open/floating or 2 V and above is a logic high).
4. Now that BDAC is set up as the desired reference voltage, the next step is to decide how far from this voltage the system voltage (typically the DC/DC converter output) is allowed to go, before shutting down the system. Select R4 and R5 to create the Under-Voltage threshold. R4 + R5 should total around $50 \mathrm{k} \Omega$, so as not to load the BDAC. OVUVTH = BDAC * (R5) / (R4 + R5).
The threshold is a percentage of whatever the BDAC voltage is. If we define delta $=($ BDAC - OVUVTH), then the SAM will take that voltage, and mirror it up, to create an internal Over-Voltage trip point of BDAC + delta, which is the same voltage above the BDAC that the UV trip point is below BDAC (the trip points are symmetrical by design). For example, if BDAC is $2.5 \mathrm{~V}, \mathrm{R} 5$ is 40 K , and R 4 is 10 K , then OVUVTH $=2.0 \mathrm{~V}$. Since the UV threshold is 0.5 V below BDAC, the internal OV threshold will be 0.5 V above BDAC, or 3.0 V . So, if during normal operation, the converter output voltage is pulled past either trip point, the START and PGOOD signals will change state, and can be used to shut down the converter. Note that there is also hysteresis for both trip points; it varies with each logic option; see Logic Options Table.
If an opamp is needed to help condition or filter the input signal at OVUVSEN, the spare one can be used. It can also be used to change the gain, if the voltage to be compared is not equal to the BDAC voltage. And if the opamp is not needed here, it can still be used for any other purpose.
There is an optional Under-Voltage Delay circuit. This allows the system to ignore an excursion below the UV
trip point for a short time period (for example, during a power-up sequence). When the UV trip point is exceeded, an external capacitor (C1 to GND) on the UVDLY pin gets charged through an internal $20 \mu \mathrm{~A}$ current source. If the OVUVSEN input is still below the trip point when the UVDLY pin reaches a nominal 5 V , it will make the internal UVD signal a logic high, and the START or PGOOD will react accordingly.

The delay time dt uses the formula $I=C$ * $d v / d t$. In this case, $\mathrm{dt}=\mathrm{C} 1$ * $5 \mathrm{~V} / 20 \mu \mathrm{~A}$. Or solve for $\mathrm{C} 1=(20 \mu \mathrm{~A})$ * $(\mathrm{dt}) / 5 \mathrm{~V}$. Practical values for C range from 100 pF (for $25 \mu \mathrm{~s}$ ) up to $0.1 \mu \mathrm{~F}$ (for 25 ms ).
5. There is an UVLO (Under-Voltage Lock-Out); also called POR (Power-On-Reset), so as not to be confused with the Under-Voltage detection. This block monitors the VDD voltage; it releases around 9.4 V as the power supply turns on, and has about 1.0 V of hysteresis. This block only affects the START and PGOOD outputs.
6. The Logic block takes the various input and internal conditions (PEN, UV, OV, UVDLY, POR), and combines them logically to create the START and PGOOD outputs. These pins require some kind of external pull-up resistor (or equivalent); the pull-ups can be to the 12 V supply, or any lower voltage compatible with the external logic. The value of the resistors depend on the pull-up voltage, the current desired, the logic voltage levels, rise or fall time considerations, etc.; A typical value would be $5 \mathrm{k} \Omega$. The FAULT latch is set by a combination of input conditions; it is reset by POR or PEN (see Logic Options).
The advantage of the latch is that a momentary fault can be saved, and the user must do something (power down or toggle PEN) to recover. But some users might call that same scenario a disadvantage. So there are three different logic options to choose from. Which one is best? Which logic signals should you use?
It depends upon what's available in the system. The PEN input is useful, for example, because it can reset the FAULT latch of the C version; the A version requires the user to power down to reset. But does the system have a signal available to do that function? The B version doesn't use a latch; if a fault condition occurs, the START and PGOOD will reflect the change; but if the fault goes away, the outputs can potentially recover on their own. So part of the choice among the logic options is whether the system is smart enough to diagnose and correct a problem, or does it just shut everything down, and wait for help.

## Small Outline Plastic Packages (SOIC)



NOTES:

1. Symbols are defined in the "MO Series Symbol List" in Section 2.2 of Publication Number 95.
2. Dimensioning and tolerancing per ANSI Y14.5M-1982.
3. Dimension "D" does not include mold flash, protrusions or gate burrs. Mold flash, protrusion and gate burrs shall not exceed 0.15mm (0.006 inch) per side.
4. Dimension "E" does not include interlead flash or protrusions. Interlead flash and protrusions shall not exceed 0.25 mm ( 0.010 inch) per side.
5. The chamfer on the body is optional. If it is not present, a visual index feature must be located within the crosshatched area.
6. " $L$ " is the length of terminal for soldering to a substrate.
7. " N " is the number of terminal positions.
8. Terminal numbers are shown for reference only.
9. The lead width " $B$ ", as measured 0.36 mm ( 0.014 inch) or greater above the seating plane, shall not exceed a maximum value of 0.61 mm ( 0.024 inch)
10. Controlling dimension: MILLIMETER. Converted inch dimensions are not necessarily exact.

M20.3 (JEDEC MS-013-AC ISSUE C)
20 LEAD WIDE BODY SMALL OUTLINE PLASTIC PACKAGE

| SYMBOL | INCHES |  | MILLIMETERS |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: |
|  | MIN | MAX | MIN | MAX |  |
| A | 0.0926 | 0.1043 | 2.35 | 2.65 | - |
| A1 | 0.0040 | 0.0118 | 0.10 | 0.30 | - |
| B | 0.013 | 0.0200 | 0.33 | 0.51 | 9 |
| C | 0.0091 | 0.0125 | 0.23 | 0.32 | - |
| D | 0.4961 | 0.5118 | 12.60 | 13.00 | 3 |
| E | 0.2914 | 0.2992 | 7.40 | 7.60 | 4 |
| e | 0.050 | BSC | 1.27 |  | BSC |
| H | 0.394 | 0.419 | 10.00 | 10.65 | - |
| h | 0.010 | 0.029 | 0.25 | 0.75 | 5 |
| L | 0.016 | 0.050 | 0.40 | 1.27 | 6 |
| N | 20 |  | 20 |  | 7 |
| $\alpha$ | $0^{0}$ | $8^{0}$ | $0^{0}$ | $8^{0}$ | - |

Rev. 0 12/93


L20.5x5
20 LEAD MICRO LEAD FRAME PLASTIC PACKAGE (COMPLIANT TO JEDEC MO-220-VHHC ISSUE C)

| SYMBOL | MILLIMETERS |  |  | NOTES |
| :---: | :---: | :---: | :---: | :---: |
|  | MIN | NOMINAL | MAX |  |
| A | - | - | 0.90 | - |
| A1 | - | - | 0.05 | - |
| A2 | - | - | 0.70 | - |
| A3 | 0.20 REF |  |  | - |
| b | 0.23 | 0.28 | 0.35 | 5,8 |
| D | 5.00 BSC |  |  | - |
| D1 | 4.75 BSC |  |  | - |
| D2 | 2.95 | 3.10 | 3.25 | 7,8 |
| E | 5.00 BSC |  |  | - |
| E1 | 4.75 BSC |  |  | - |
| E2 | 2.95 | 3.10 | 3.25 | 7,8 |
| e | 0.65 BSC |  |  | - |
| k | 0.25 | - | - | - |
| L | 0.50 | 0.60 | 0.75 | 8 |
| N | 20 |  |  | 2 |
| Nd | 5 |  |  | 3 |
| Ne | 5 |  |  | 3 |
| P | - | - | 0.60 | - |
| $\theta$ | - | - | 12 | - |

NOTES:

1. Dimensioning and tolerancing per ASME Y14.5-1994.
2. N is the number of terminals.
3. Nd is the number of terminals in the X direction, and Ne is the number of terminals in the Y direction.
4. Controlling dimension: Millimeters. Converted dimensions to inches are not necessarily exact. Angles are in degrees.
5. Dimension $b$ applies to the plated terminal and is measured between 0.20 mm and 0.25 mm from the terminal tip.
6. The Pin \#1 identifier exists on the top surface as an indentation mark in the molded body.
7. Dimensions D2 and E2 are the maximum exposed pad dimensions for improved grounding and thermal performance.
8. Nominal dimensions provided to assist with PCB Land Pattern Design efforts, see Technical Brief TB389.

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