Monolithic Digital IC

LB11997H



# Three-Phase Brushless Motor Driver for CD-ROM Spindle Drive

#### Preliminary

#### **Overview**

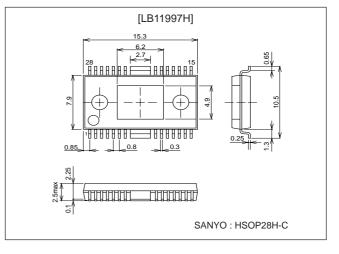
The LB11997H is a 3-phase brushless motor driver especially suited for CD-ROM spindle motor drives.

#### **Functions**

- Current linear drive
- Control V type amplifier
- Separate power supply for output upper side bias circuit allows low output saturation by boosting this power supply only (useful for 5V power supply types).
- Upper side current detection technique reduces loss voltage of current detection resistor. Voltage drop caused by this resistor reduces internal power dissipation of IC.
- Built-in short braking circuit
- Built-in reverse blocking circuit
- Hall FG output
- Built-in S/S function
- Built-in current limiter circuit (selectable, 2 steps)
- Built-in Hall power supply
- Built-in thermal shutdown circuit
- Supports 3.3V DSP

#### **Package Dimensions**

unit: mm 3234-HSOP28H-C



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SANYO Electric Co., Ltd. Semiconductor Company TOKYO OFFICE Tokyo Bldg., 1-10, 1 Chome, Ueno, Taito-ku, TOKYO, 110-8534 JAPAN

# Specifications

### Absolute Maximum Ratings at Ta = $25^{\circ}C$

Parameter	Symbol	Conditions	Ratings	Unit
Maximum supply voltage	V <sub>CC</sub> 1 max		7.0	V
	V <sub>CC</sub> 2 max		14.4	V
	V <sub>CC</sub> 3 max		14.4	V
Applied output voltage	V <sub>O</sub> max		14.4	V
Applied intput voltage	V <sub>IN</sub> max		V <sub>CC</sub> 1	V
Output current	I <sub>O</sub> max		1.3	А
Allowable power dissipation	Pd max		0.8	W
Operating temperature	Topr		-20 to +75	°C
Storage temperature	Tstg		-55 to +150	°C

### Operating Conditions at Ta = $25^{\circ}C$

Parameter	Symbol	Conditions	Ratings	Unit
Power supply voltage	V <sub>CC</sub> 1		4 to 6	V
	V <sub>CC</sub> 2	≥ V <sub>CC</sub> 1	4 to 13.6	V
	V <sub>CC</sub> 3		4 to 13.6	V

#### Sample Application at Ta = $25^{\circ}C$

Parameter	Symbol	Conditions	Ratings	Unit
12V type	V <sub>CC</sub> 1	Regulated voltage	4 to 6	V
	$V_{CC}^2 = V_{CC}^3$	Unregulated voltage	4 to 13.6	V
5V type	$V_{CC}1 = V_{CC}3$	Regulated voltage	4 to 6	V
	V <sub>CC</sub> 2	Boost-up voltage or regulated voltage (Note)	4 to 13.6	V

Note: When boost-up voltage is used at  $V_{CC}^2$ , output can be set to low-saturation.

# Electrical Characteristics at Ta = 25°C, $V_{CC}1$ = 5V, $V_{CC}2$ = $V_{CC}3$ = 12V

Parameter	Symbol Conditions		Ratings			Unit
i urumotor	Cymbol		min	typ	max	01
[Power supply current]		-				
Power supply current	I <sub>CC</sub> 1	$V_{C} = V_{CREF}$		8		mA
	I <sub>CC</sub> 2	$V_{C} = V_{CREF}$		0		mA
	I <sub>CC</sub> 3	$V_{C} = V_{CREF}$		150	250	μA
Output idle current	I <sub>CC</sub> 10Q	$V_{S/S} = 0V$			200	μA
	I <sub>CC</sub> 2OQ	$V_{S/S} = 0V$			30	μΑ
	I <sub>CC</sub> 3OQ	$V_{S/S} = 0V$			30	μΑ
[Output]						
Saturation voltage, upper side 1	V <sub>OU</sub> 1	$I_{O} = -0.5A, V_{CC}1 = 5V, V_{CC}2 = V_{CC}3 = 12V$		1.0		V
lower side 1	V <sub>OD</sub> 1	$I_0 = 0.5A, V_{CC}1 = 5V, V_{CC}2 = V_{CC}3 = 12V$		0.3		V
Saturation voltage, upper side 2	V <sub>OU</sub> 2	$I_{O} = -0.5A, V_{CC}1 = V_{CC}3 = 5V, V_{CC}2 = 12V$		0.3		V
lower side 2	V <sub>OD</sub> 2	$I_{O} = 0.5A, V_{CC}1 = V_{CC}3 = 5V, V_{CC}2 = 12V$		0.3		V
Current limiter setting voltage	V <sub>CL</sub> 1	$R_{RF} = 0.33\Omega$ , LMC; OPEN		0.24		V
	V <sub>CL</sub> 2	R <sub>RF</sub> = 0.33Ω, LMC; GND		0.35		V
[Hall amplifier]	•				••	
Common mode input voltage range	V <sub>HCOM</sub>		1.2		V <sub>CC</sub> 1–1.0	V
Input bias current	I <sub>HIB</sub>			1		μA
Minimum Hall input level	V <sub>HIN</sub>		60			mV <sub>P-P</sub>
[S/S pin]						
High level voltage	V <sub>S/SH</sub>		2.0		V <sub>CC</sub> 1	V
Low level voltage	V <sub>S/SL</sub>				0.7	V
Input current	I <sub>S/SI</sub>	$V_{S/S} = 5V$			200	μA
Leakage current	I <sub>S/SL</sub>	$V_{S/S} = 0V$	-30			μA
[Control]						
V <sub>C</sub> pin input current	I <sub>VC</sub>	V <sub>C</sub> = V <sub>CREF</sub> = 1.65V			1	μA
V <sub>CREF</sub> pin input current	IVCREF	V <sub>C</sub> = V <sub>CREF</sub> = 1.65V			1	μA
Voltage gain	GV <sub>CO</sub>	$\Delta V_{RF} / \Delta V_{C}$		0.35		times
Startup voltage	V <sub>CTH</sub>	V <sub>CREF</sub> = 1.65V	1.5		1.8	V
Startup voltage width	ΔV <sub>CTH</sub>	V <sub>CREF</sub> = 1.65V	50		150	mV
[Hall power supply]						
Hall power supply voltage	V <sub>H</sub>	I <sub>H</sub> = 5 mA		0.8		V
Allowable current	I <sub>H</sub>		20			mA
[Thermal shutdown]						
Operating temperature	T <sub>TSD</sub>	Design target value	150	180	210	°C
Hysteresis	ΔT <sub>TSD</sub>	Design target value		15		°C
[Short braking]						
Brake pin at High level	V <sub>BRH</sub>		4		5	V
Brake pin at Low level	V <sub>BRL</sub>		0		1	V

Note:

• During S/S OFF (standby), the Hall comparator is at High.

• Design target values are not measured.

#### **Truth Table**

$\smallsetminus$	Course Cials		Hall input	Control	
	Source -> Sink	U	V	W	V <sub>C</sub>
1	Phase W -> Phase V	н	Н	1	Н
	Phase V -> Phase W			-	L
2	Phase W -> Phase U	н	L	1	Н
-	Phase U -> Phase W			L	L
3	Phase V -> Phase W	1	L	н	Н
5	Phase W -> Phase V				L
4	Phase U -> Phase V		н	1	Н
4	Phase V -> Phase U			L	L
5	Phase V -> Phase U	н		н	Н
	Phase U -> Phase V		L	11	L
6	Phase U -> Phase W	L	Н	н	Н
0	Phase W -> Phase U				L

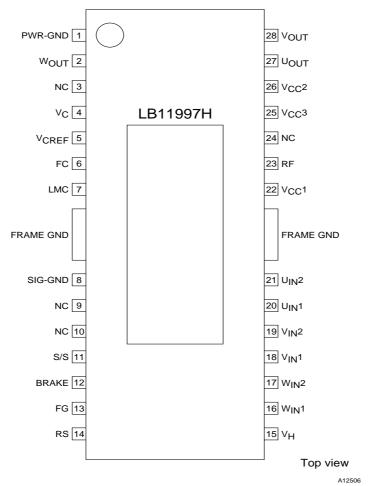
Input:

H: Input 1 is higher in potential than input 2 by at least 0.2V.L: Input 1 is lower in potential than input 2 by at least 0.2V.

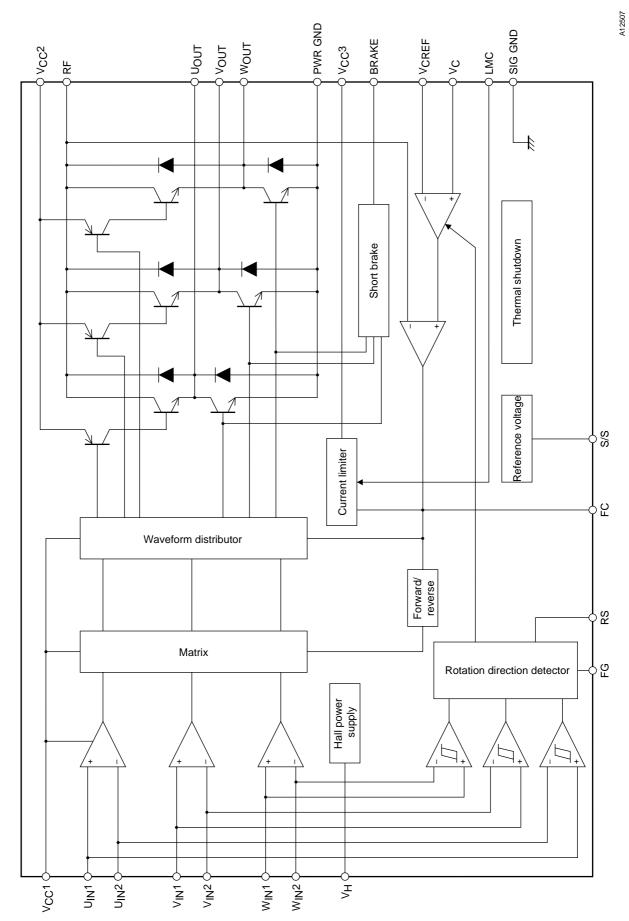
### **Brake Operation Truth Table**

BRAKE pin	Operation	
н	Short brake	
Low or open	Normal rotation	

#### **Pin Assignment**



# **Block Diagram**



# **Pin Description**

Pin number	Pin name	Pin voltage	Equivalent circuit	Pin function
26	V <sub>CC</sub> 2	4V to 13.6V		Source side predrive voltage supply pin.
25	V <sub>CC</sub> 3	4V to 13.6V		Constant current control amplifier voltage supply pin.
22	V <sub>CC</sub> 1	4V to 6V		Power supply pin for all circuits except output transistors, source predriver, and constant current control amplifier.
14	RS		100μA ↓ ¥10kΩ ↓ ↓ ↓ ↓ ↓ ↓ ↓ ↓ ↓ ↓ ↓ ↓ ↓ ↓ ↓ ↓ ↓ ↓ ↓	Reverse detector pin. Forward rotation: High Reverse rotation: Low
13	FG		A12508	1 Hall element waveform Schmitt comparator composite output.
20 21	U <sub>IN</sub> 1 U <sub>IN</sub> 2		V <sub>CC</sub> 1	U phase Hall element input and reverse detector U phase Schmitt comparator input pin. Logic High indicates U <sub>IN</sub> 1 > U <sub>IN</sub> 2.
18 19	V <sub>IN</sub> 1 V <sub>IN</sub> 2	1.2V to V <sub>CC</sub> 1–1V		V phase Hall element input and reverse detector V phase Schmitt comparator input pin.
16 17	W <sub>IN</sub> 1 W <sub>IN</sub> 2		25μA	Logic High indicates $V_{IN}1 > V_{IN}2$ . W phase Hall element input and reverse detector W phase Schmitt comparator input pin. Logic High indicates $W_{IN}1 > W_{IN}2$ .
15	V <sub>H</sub>		Vcc1 75μA 30kΩ 2kΩ 2kΩ 2kΩ 2kΩ 30kΩ 30kΩ 30kΩ	Hall element lower side bias voltage supply pin.
11	S/S	0V to V <sub>CC</sub> 1	Vcc1 11 50kΩ \$ 11 412511	When this pin is at 0.7V or lower, or when it is open, all circuits are inactive. When driving motor, set this pin to 2V or higher.
8	SIG GND			GND pin for all circuits except output.
6	FC		$V_{CC1}$	Control loop frequency characteristics compensator pin. Connecting a capacitor between this pin and GND prevents closed loop oscillation in current limiting circuitry.

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Pin number	Pin name	Pin voltage	Equivalent circuit	Pin function
5	V <sub>CREF</sub>	0V to V <sub>CC</sub> 1 -1.5V	15μA (μ) 25μA (μ) 15μA	Control reference voltage supply pin. Determines control start voltage.
4	v <sub>c</sub>	0V to V <sub>CC</sub> 1		Speed control voltage supply pin. V type control technique $V_C > V_{CREF}$ : Forward $V_C < V_{CREF}$ : Slowdown (Reverse-blocking circuit prevents reverse rotation.)
2	W <sub>OUT</sub>			W phase output.
1	PWR GND			Output transistor GND.
28	V <sub>OUT</sub>			V phase output.
27	U <sub>OUT</sub>		3.9Ω	U phase output. Upper side output NPN transistor
23	RF		27)28)2) 3.9Ω 	collector pin (common for all 3 phases). For current detection, connect resistor between $V_{CC}3$ pin and RF pin. Constant current control and current limiter works by detecting this voltage.
7	LMC		VCC1	When this pin is connected to GND, the limiter setting current is increased by a factor of 1.5.
12	BRAKE		100μA VCC1   75kΩ 12   50kΩ 12	Short brake pin. BRAKE: High -> Short brake operation Low/Open -> Motor drive operation

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