

LB1910N

FDD Spindle Motor Driver

Overview

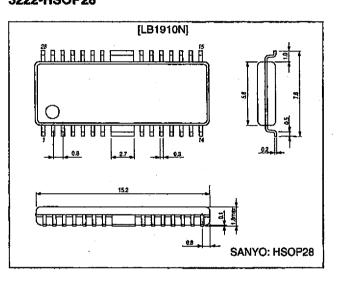
The LB1910N is a 3-phase disc drive motor driver that is optimal for use as a 3.5-inch FDD spindle motor driver.

Functions and Features

- Three-phase full-wave linear driver
- Digital speed control circuit
- Start and stop circuits (active low)
- RPM switching H: 300 rpm L: 360 rpm
- Current limiter circuit
- · Built-in index comparator
- Thermal shutdown circuit

Package Dimensions

unit: mm 3222-HSOP28



Specifications

Absolute Maximum Ratings at Ta = 25°C

Parameter	Symbol	Conditions	Ratings	Unit
Maximum supply voltage	V _{CC} max		7.0	V
Maximum output current	I _O max1	l≤0.5s	1.0	A
Maximum steady-state output current	I _O max2	<u> </u>	0.7	A
Allowable power dissipation	Pd max	Independent iC	0.5	w
Operating temperature	Topr	······································	-20 to +80	°C
Storage temperature	Tstg	······································	-40 to +150	•C

Allowable Operating Ranges at Ta = 25°C

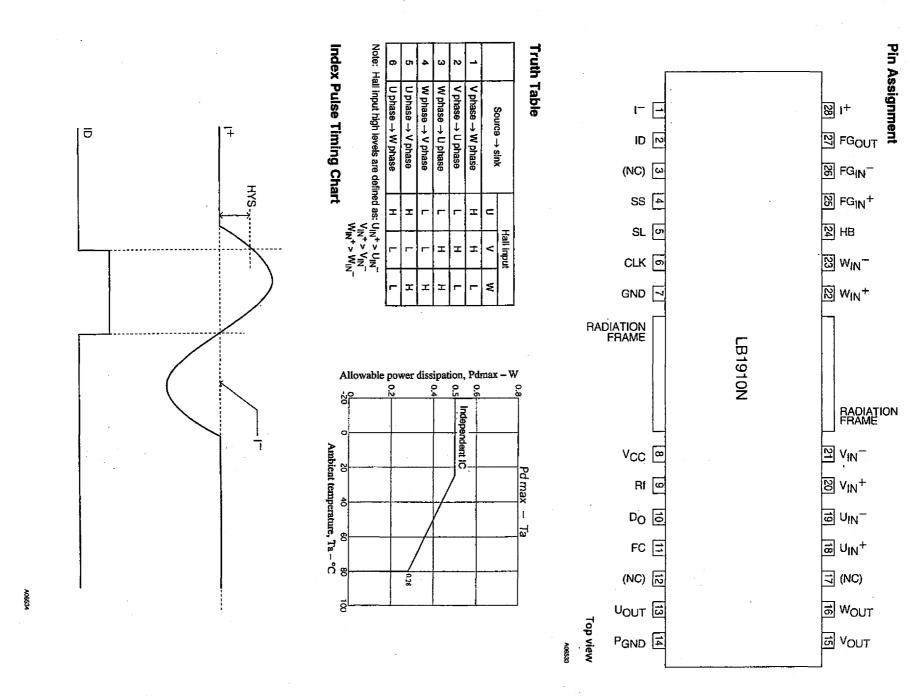
Parameter	Symbol	Conditions	Ratings	Unit
Recommended supply voltage	Vcc		4.2 to 6.5	v

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Electrical Characteristics at Ta = 25°C, V_{CC} = 5 V

Parameter	Symbol	Conditions	min	typ	max	Unit
Ourseast datain	Icco	S/S = 5 V (standby)		····	10	μA
Current drain	lcc	S/S = 0 V (steady state)		12	18	mA
SL bias current	I _{SL}	V _{SL} = 0 V			10	μA
SL input low-level voltage	V _{SLL}		0		1.0	٧
SL input high-level voltage	VSLH		3.5		V _{CC}	v
S/S blas current	I _{S/S}			180	270	μA
S/S tow-level voltage	V _{S/SL}	· · · · · · · · · · · · · · · · · · ·	0		0.8	٧
S/S high-level voltage	V _{S/SH}		3.5		V _{CC}	v
Hall amplifier input bias current	I _{HB}				10	μA
Common-mode Input voltage range	Vh		1.5		V _{CC} - 1.0	V
Differential input voltage range	Vdif		50		200	mVp-p
Hall bias output voltage	VH	I _H = 5 mA		0.8		V
Leakage current	I _{HE}	S/S = 5 V			±10	μA
Output saturation voltage	Vsat	I _O = 0.7 A, sink + source		1.3	1.8	v
Output leakage current	loL				1.0	mA
Current limiter	Vlim		0.27	0.3	0.33	v
Control amplifier voltage gain	G _C			-7		dB
Voltage gain difference between phases	∆G _C	· · · · · · · · · · · · · · · · · · ·			±1	dB
V/I conversion source current	1+	· · · · · · · · · · · · · · · · · · ·	9	14	19	μA
V/I conversion sink current	1		-9	14	-19	. μΑ
V/I conversion current ratio	+/ -		0.8	1.0	1.2	
DSC buffer input current	IDSC				1.0	μA
FG Schmitt hysteresis	ΔVsh	*		50		mV
Speed discriminator counts	N			1041.5		
Discriminator operating frequency	۶ _D	*			1.1	MHz
Oscillator frequency range	Fosc	*			1.1	MHz
Index Input hysteresis	VIDH		18	23	28	mV
Index input	VIDO	I _O = 2 mA	-5	0	+5	mV
Index output low-level voltage	VIDL	$I_0 = 2 \text{ mA}$			0.4	v
Index output leakage current	IDL				±10	μA
FG amplifier voltage gain	G _{FG}	*		48		dB
FG amplifier input offset	V _{FG O}				±10	mV
FG amplifier Internal reference voltage	V _{FG B}		2.2	2.5	2.8	v
Thermal shutdown temperature	TSD	*	150	180		°C
Hysteresis	ΔTSD	*	· · ·	40		°C

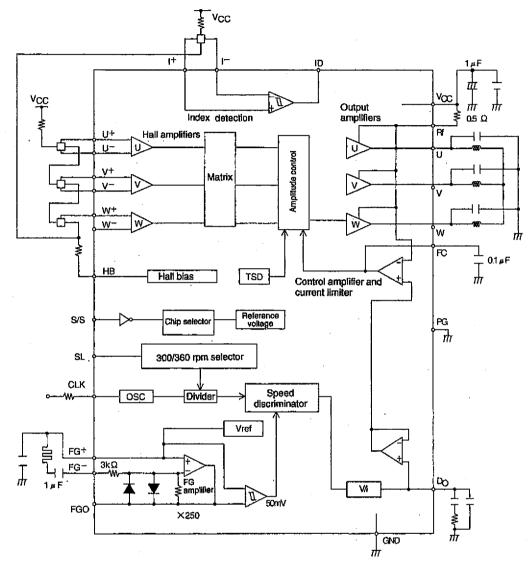
Note: * Items marked with an asterisk are design target values and are not measured.



LB1910N

No. 5562-3/7

Block Diagram



A06535

Pin Functions

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Pin No.	Symbol	Pin voltage	Equivalent circuit diagram	Function
18 19 20 21 22 23	U _{IN} + U _{IN} - V _{IN} + V _{IN} - W _{IN} + W _{IN} -	1.5 V min V _{CC} – 1.0 V max	$ \begin{array}{c} 18 \\ 20 \\ 22 \\ 18 \\ 22 \\ 18 \\ 22 \\ 18 \\ 18 \\ 22 \\ 18 \\ 18 \\ 18 \\ 18 \\ 18 \\ 18 \\ 18 \\ 18$	U phase Hall element input V phase Hall element input W phase Hall element input
24	нв	0.8 V typ (I _H = 5 mA)	24 77 77 77 77 77 77 77 77 77 806537	Minus side connection for providing the Hall blas current This pin becomes open in the stopped state, thus cutting the Hall blas current.
25 26 27	FG _{IN} ≁ FG _{IN} − FG _{OUT}	2.5 V	26 WCC 27 75 75 75 75 75 75 75 75 75 7	 FG amplifier plus input A 2.5-V reference voltage is generated internally. FG amplifier minus input FG amplifier output
28 1	+ }-		28 2000 1 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000	Index input
2	D	L: 0.4 V max H: 4.5 V min	2 	Index output

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Pin No.	Symbol	Pin voltage	Equivalent circuit diagram	Function
4	SS	L: 0.8 Ý max H: 3.5 V min		Start/stop mode switching This is an active-low input.
5	SL	L: 1.0 V max H: 3.5 V min		Rotational speed switching
6	CLK	L: 1.0 V max H: V _{CC} – 1.0 V min		Reference clock input A 1-MHz input frequency corresponds to speeds of 300 and 360 rpm.
7	GND			 Ground This pin, pin 14, and the frame must all be grounded together.
8	Vcc			Power supply This voltage must be stabilized so that ripple and noise do not enter the IC,
9	Rf			Output current detection The output current is detected as a voltage by connecting the resistor RI between this pin and V_{CC} . The current limiter operates by detecting the voltage on this pin.
10	DO			Speed discriminator
11	F _C			Frequency characteristics compensation Current control system loop oscillation is prevented by connecting a capacitor between this pin and ground.

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Pin No.	Symbol	bol Pin voltage Equivalent circult diagram		Function
13 15 16	υ _{ουτ} ν _{ουτ} Ψουτ			U phase output V phase output W phase output
14	PGND			Output transistor ground connection

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